



Overview of Magnet design issues

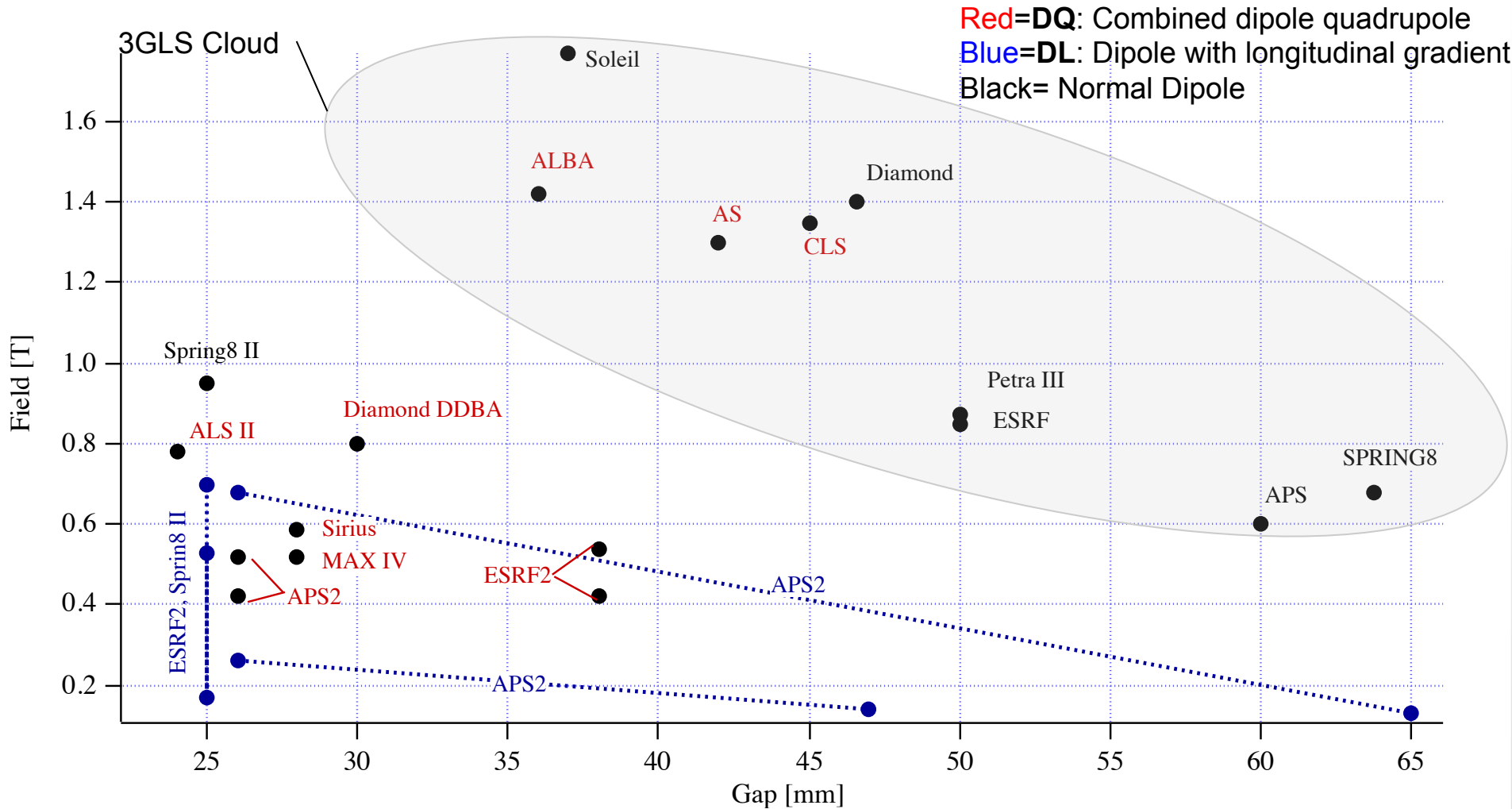
J. Chavanne, G. Le Bec , J F.Bouteille

On Behalf
The ESRF ASD

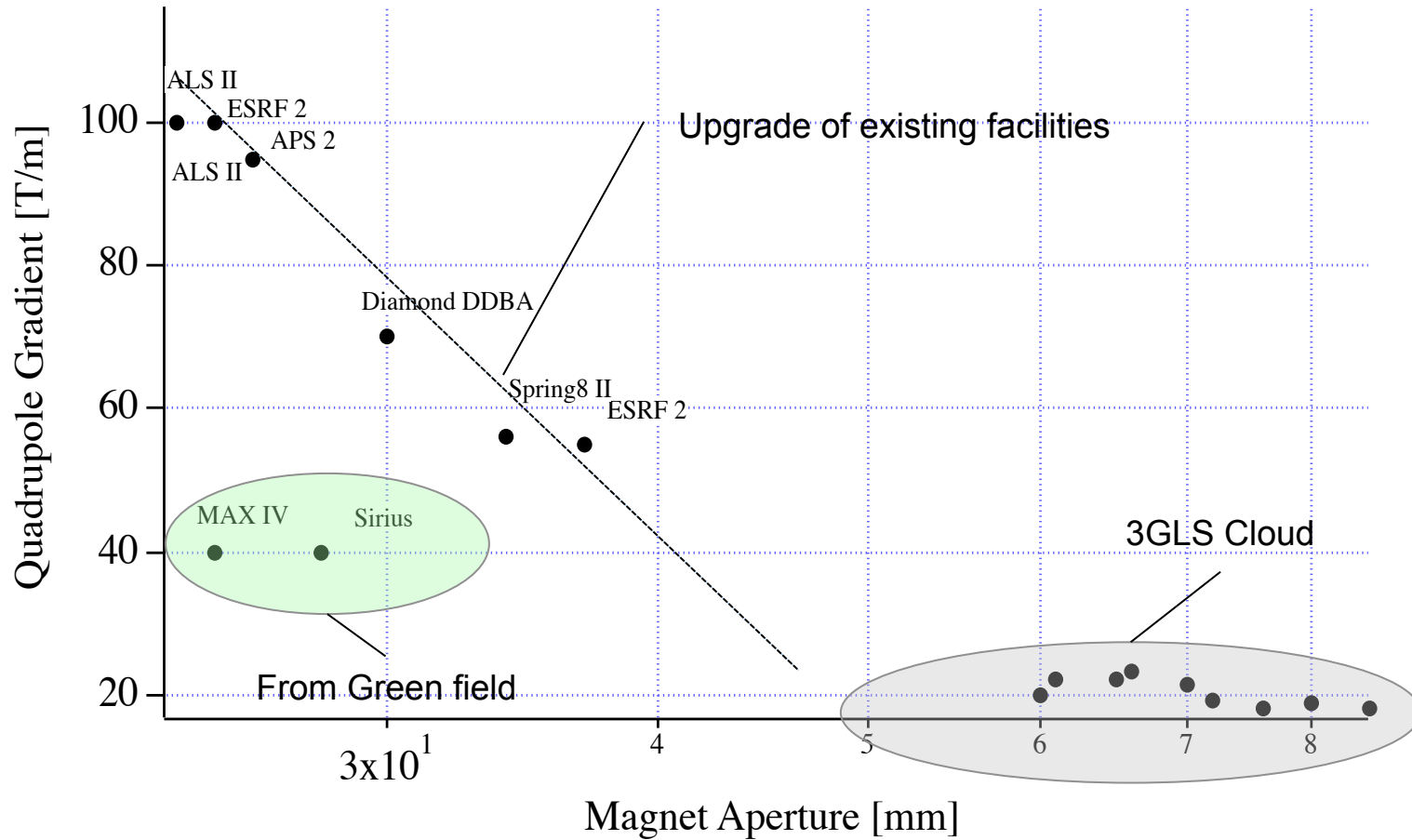
1. Magnets in DLSRs

2. Magnetic design

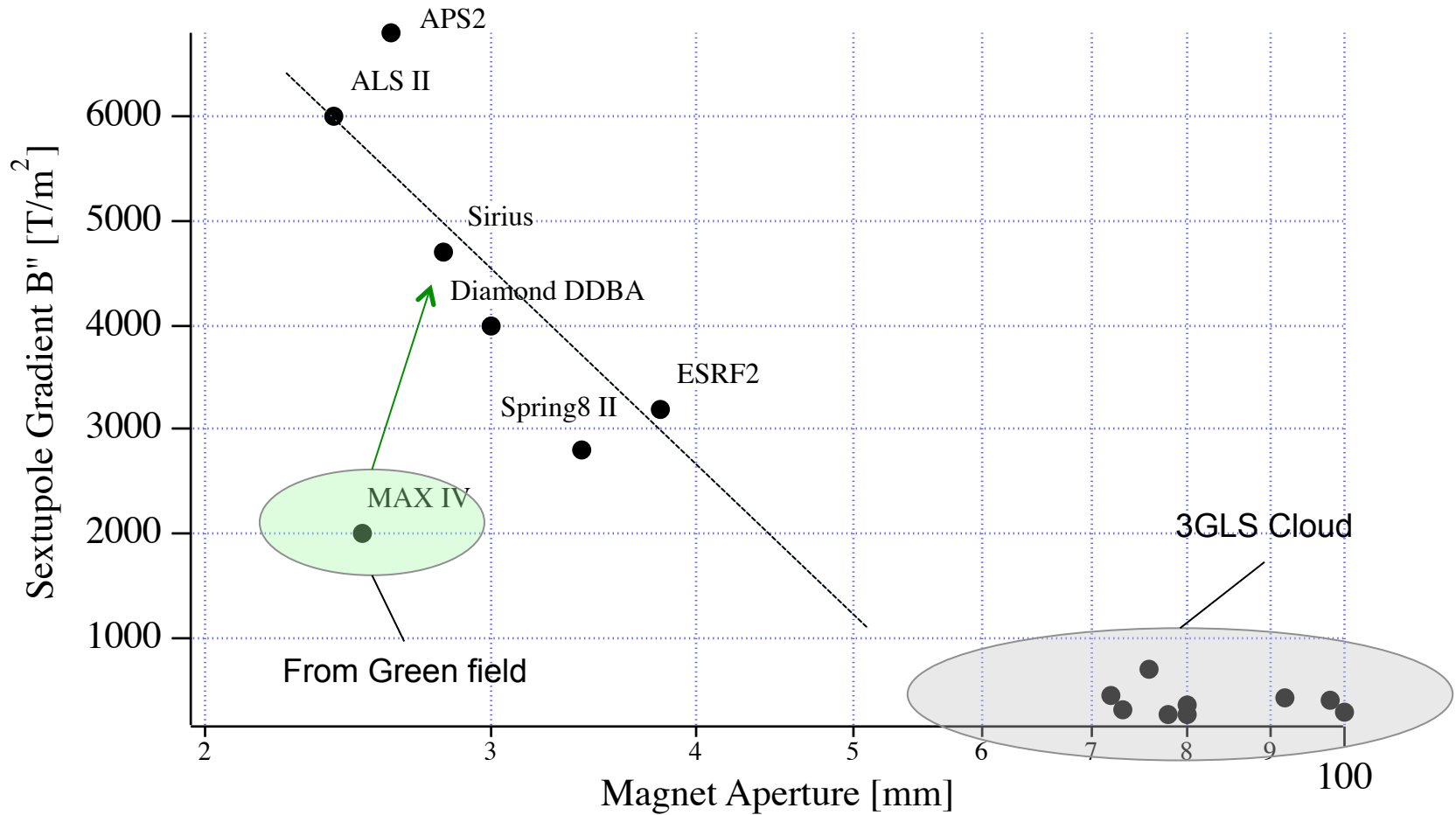
3. Magnetic measurements/alignment



No more standard dipoles in DLSRs



Quadrupole gradient primarily increased with reduction of aperture
 Mostly demanding for upgrade projects (has to cope with existing cell length)



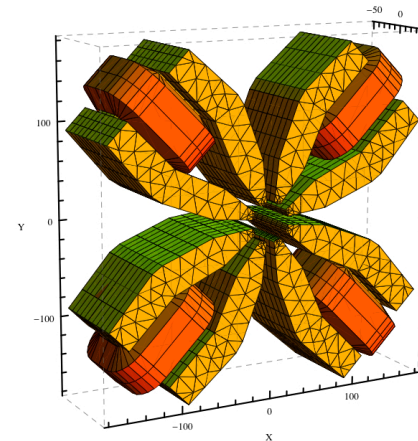
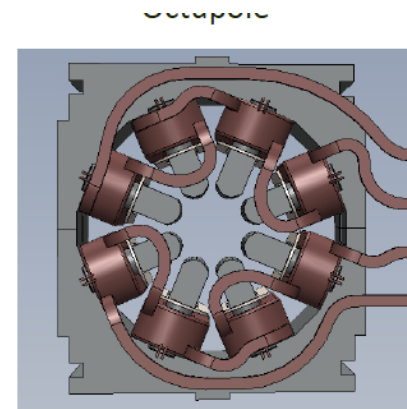
Sextupole gradient ~ same observation as for quadrupoles

. Emerge as lattice components in some projects

- MAX IV:
 - 65 000 T/m³
 - Bore radius 12.5 mm

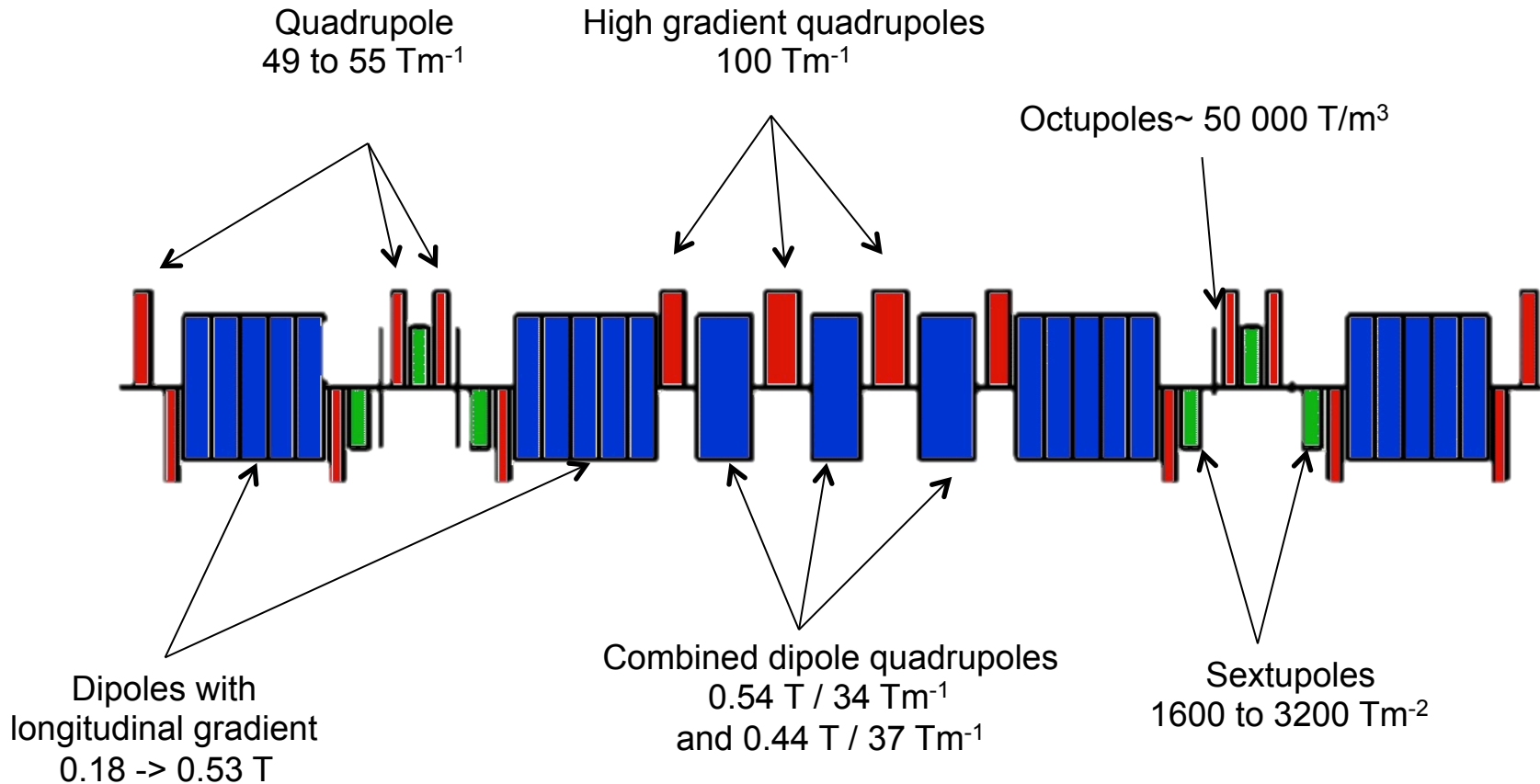
- ESRF 2
 - 50 000 T/m³
 - Bore radius 20 mm

- OTHERS



1. Magnet apertures need (must) be dramatically reduced
 - Conventional magnet technology (“a la 3GLS”)
 - Reasonable magnet size & wall plug power

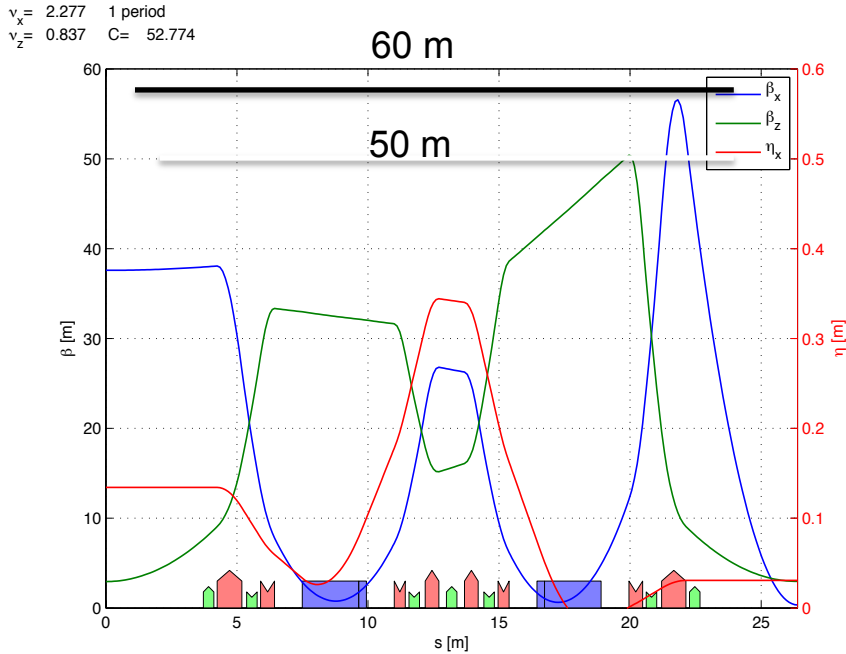
2. Distinction between “ Green Field” projects and upgrade projects
 - Upgrade projects have additional constraints
 - Use exiting ring
 - Same cell length , same source points for Insertion Devices
 - Compact magnet lattice smaller integrated drift space/cell (9 m -> 3m @ ESRF)



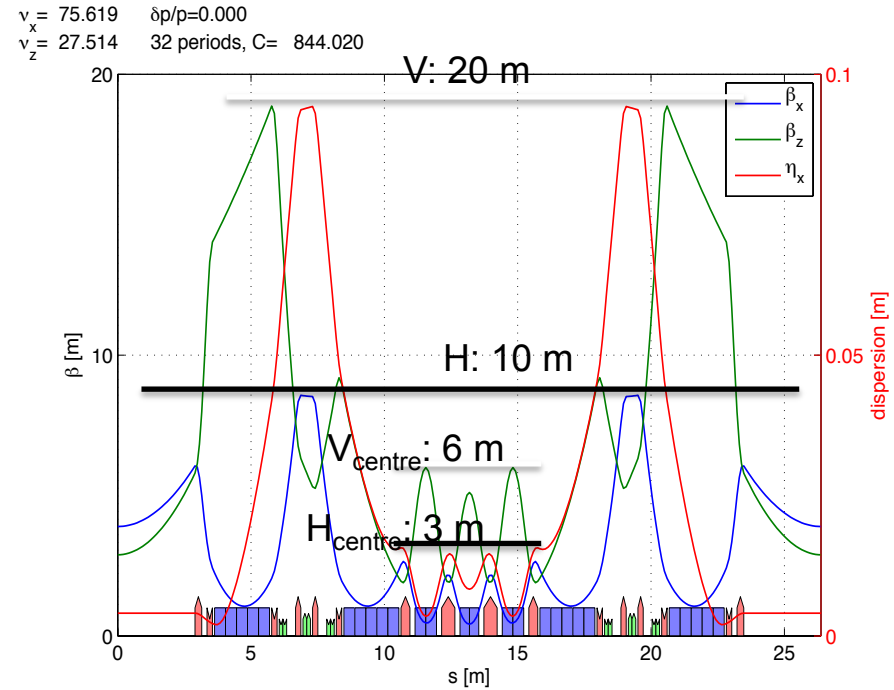
Definition of Good Field Region (GFR) is important for magnet design

- Small magnet aperture
- GFR size mostly defined by injection requirements (efficiency)
 - Emittance in booster
 - On axis/off axis injection
- Smaller beta function in MBAs is helping in this context ->smaller GFR
- Magnets may need to include pole shaping in some cases
- Vertical gap between poles/coils for photon beam extraction
- Systematic Beam tracking analysis definitely crucial
 - Error allowance
 - Sensitivity to different multipoles
 - Relevance of optimizations ...
 - etc

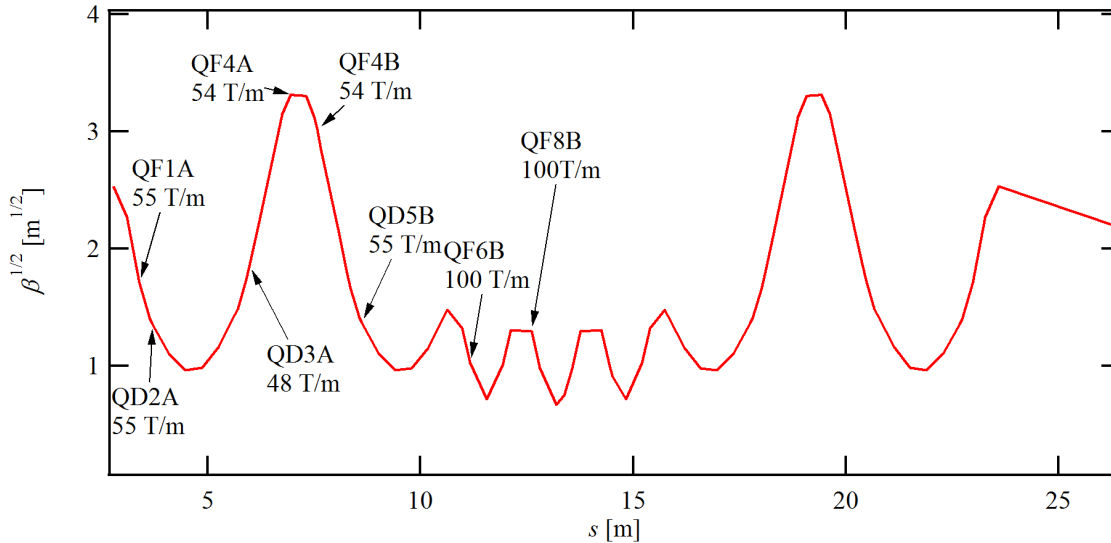
Beam stay clear derived from beta ^{1/2} scaling



Present lattice



New 7BA Lattice



Starting point

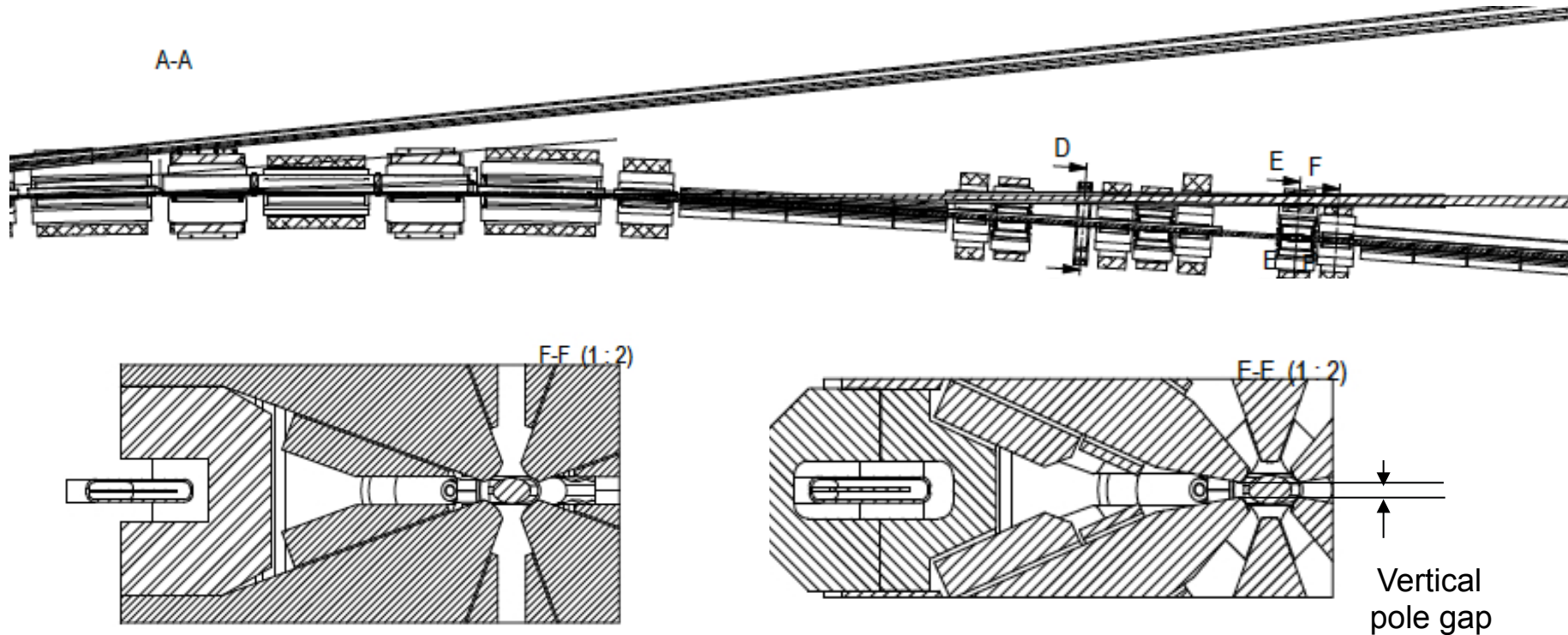
| Magnet | Tolerance in GFR |
|---------|------------------|
| 2-poles | $DB/B < 10^{-4}$ |
| 4-poles | $DG/G < 10^{-3}$ |
| 6-poles | $DH/H < 10^{-2}$ |

Field quality specs to be refined

| Zone 1 | Horizontal [mm] | Vertical [mm] |
|----------------------------------|-----------------|---------------|
| Vacuum chamber aperture (radius) | 15 | 10 |
| Good field region (radius) | 13 | 9 |

| Zone 2 (high gradient) | Horizontal [mm] | Vertical [mm] |
|----------------------------------|-----------------|---------------|
| Vacuum chamber aperture (radius) | 8.3 | 5.5 |
| Good field region (radius) | 7 | 5 |

Photon beam path to beamline



Vertical pole gap important impact on magnet design

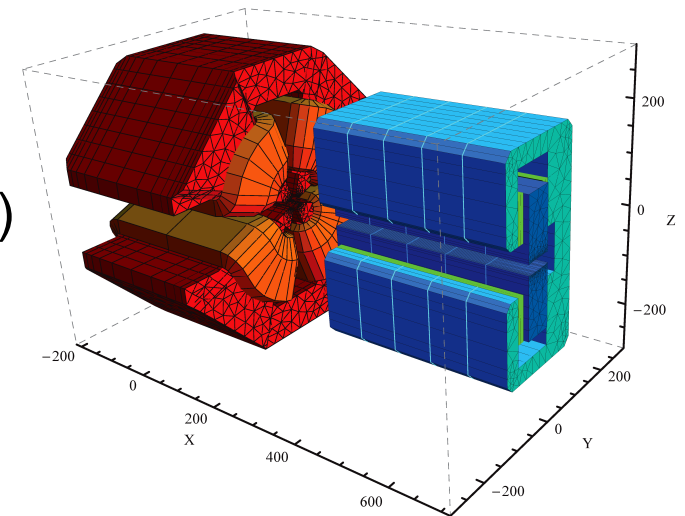
- Field strength
- field quality
- More difficult for high order multipole magnets

Tools

- 3D magnetic simulation & magnetic tracking in magnet (Radia)
- Optimization toolbox

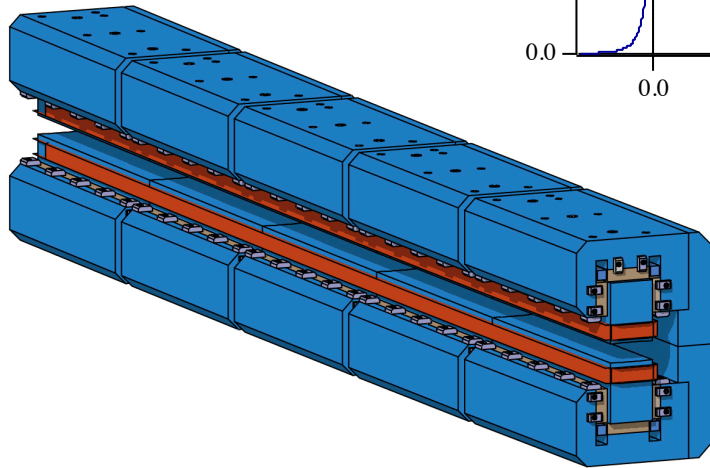
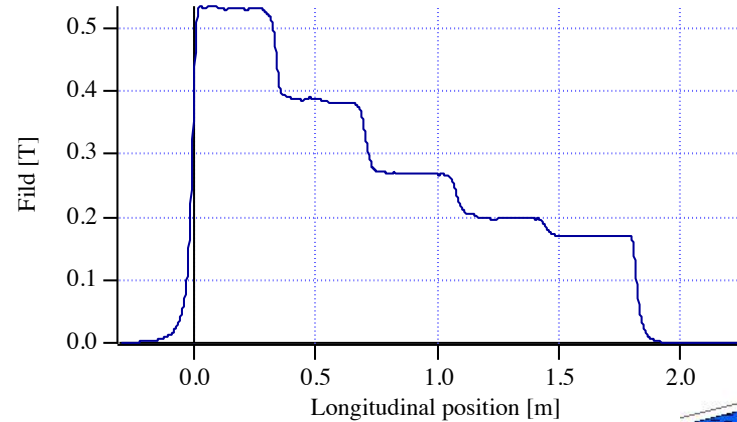
Design methods & studies

- Shape optimization (can be helpful)
- Energy efficiency
- Sensitivity analysis (small aperture)
- Interaction between magnets (compact lattice)

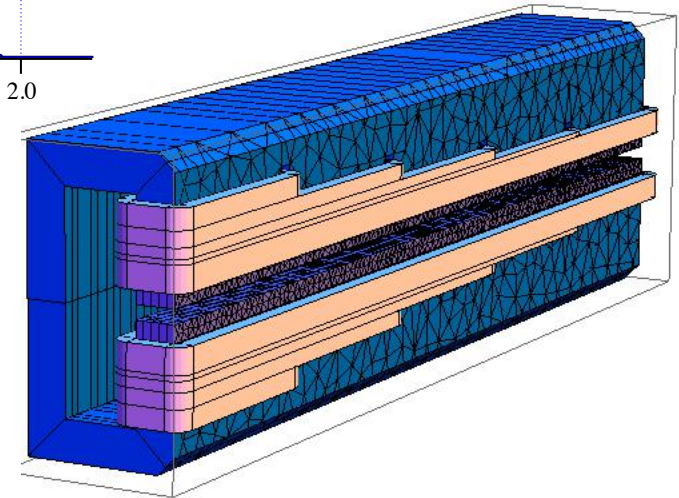


Coming on the scene for emittance reduction (ESRF2, APS 2)

- Significant L gradient: 0.5 T \rightarrow 0.15 T over \sim 2m



Example: ESRF DLS
Under study



Permanent Magnet based DL magnet
0.53 T-0.18 T, constant gap
Iron weight 575 kg, Pm weight 30 kg
 \pm 2% Field tuning with small coil

Resistive DL magnets
0.53 T – 0.18 T constant gap
1.5 kW. 1600 kg Iron +coils

Two families of DQs

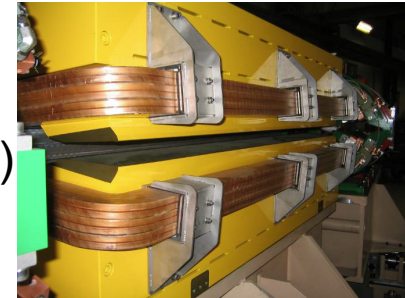
Low to moderate gradient

| | B at beam [T] | Gradient [T/m] | Aperture [mm] |
|--------------|---------------|----------------|---------------|
| MAX IV | 0.52 | 8.6 | 28 |
| Sirius | 0.584 | 7.8 | 28 |
| Diamond DDBA | 0.8 | 14.4 | 30 |
| ESRF2 DQ1 | 0.54 | 37 | 38 |
| ESRF2 DQ2 | 0.42 | 48 | 38 |
| APS 2 | 0.5 | 38 | 26 |
| ALS II | 0.78 | 50 | 24 |

High gradient

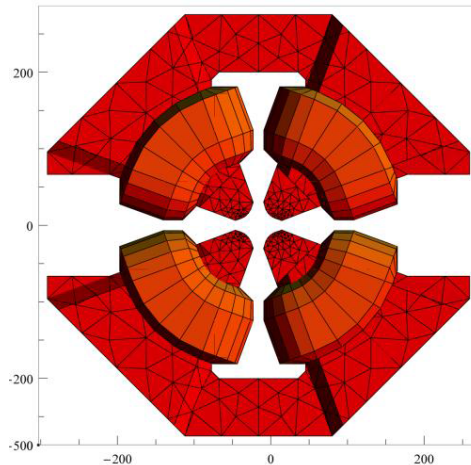
Low gradient DQs: magnet derived from modified dipole

- Pole shaping
- In use in some 3GLS facilities (ex : ALBA, AS, CLS, SPEAR 3)



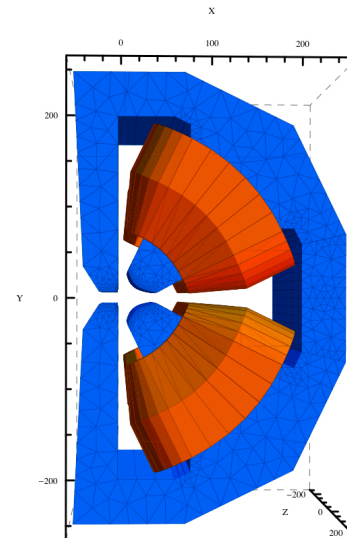
High gradient DQs: magnet derived from quadrupole

- Pole shaping may be necessary
- Different designs
- High field on beam= large offset -> difficult GFR



Quadrupole offset
ESRF DQ 0.57 T-35 T/m 38mm aperture

Or

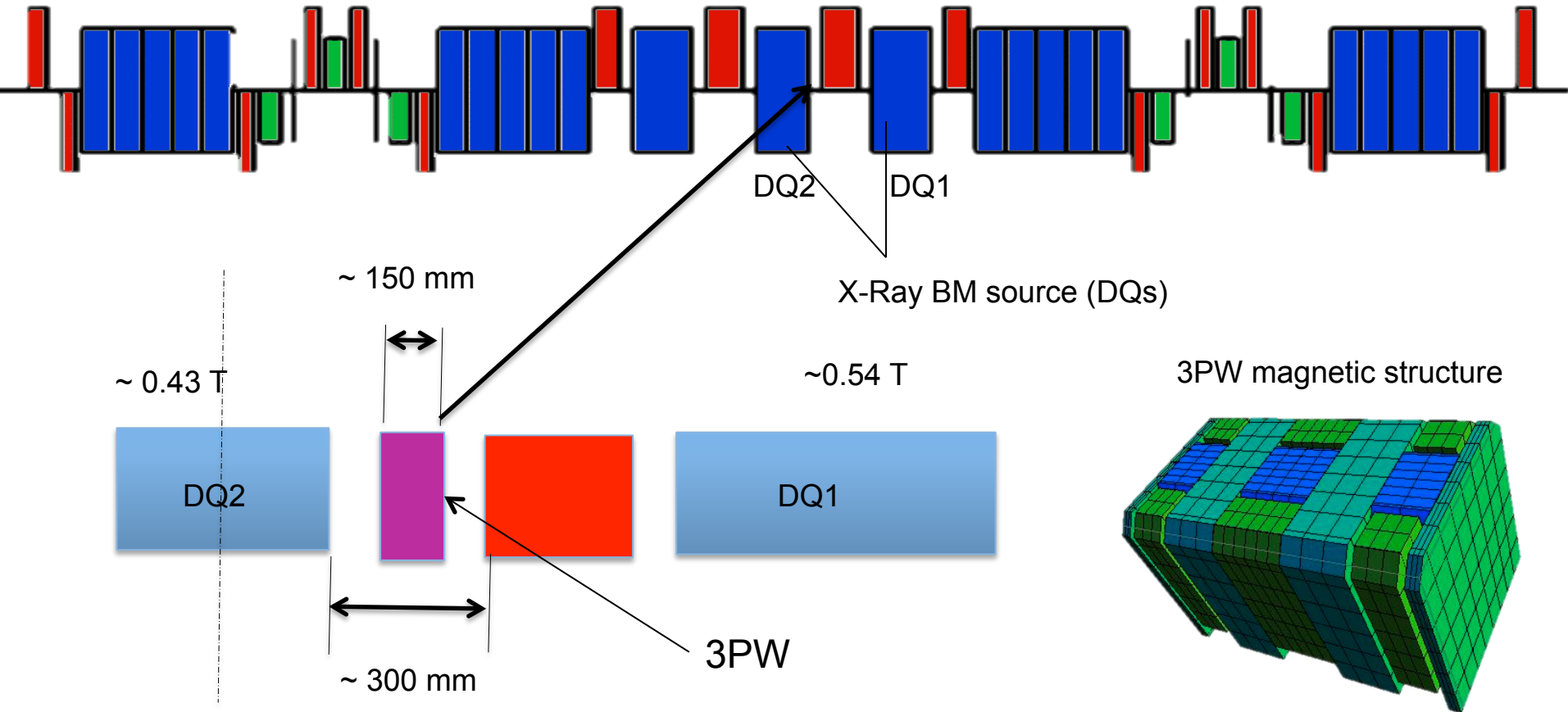


Half quadrupole
ESRF DQ 0.57 T-35 T/m 20 mm bore radius

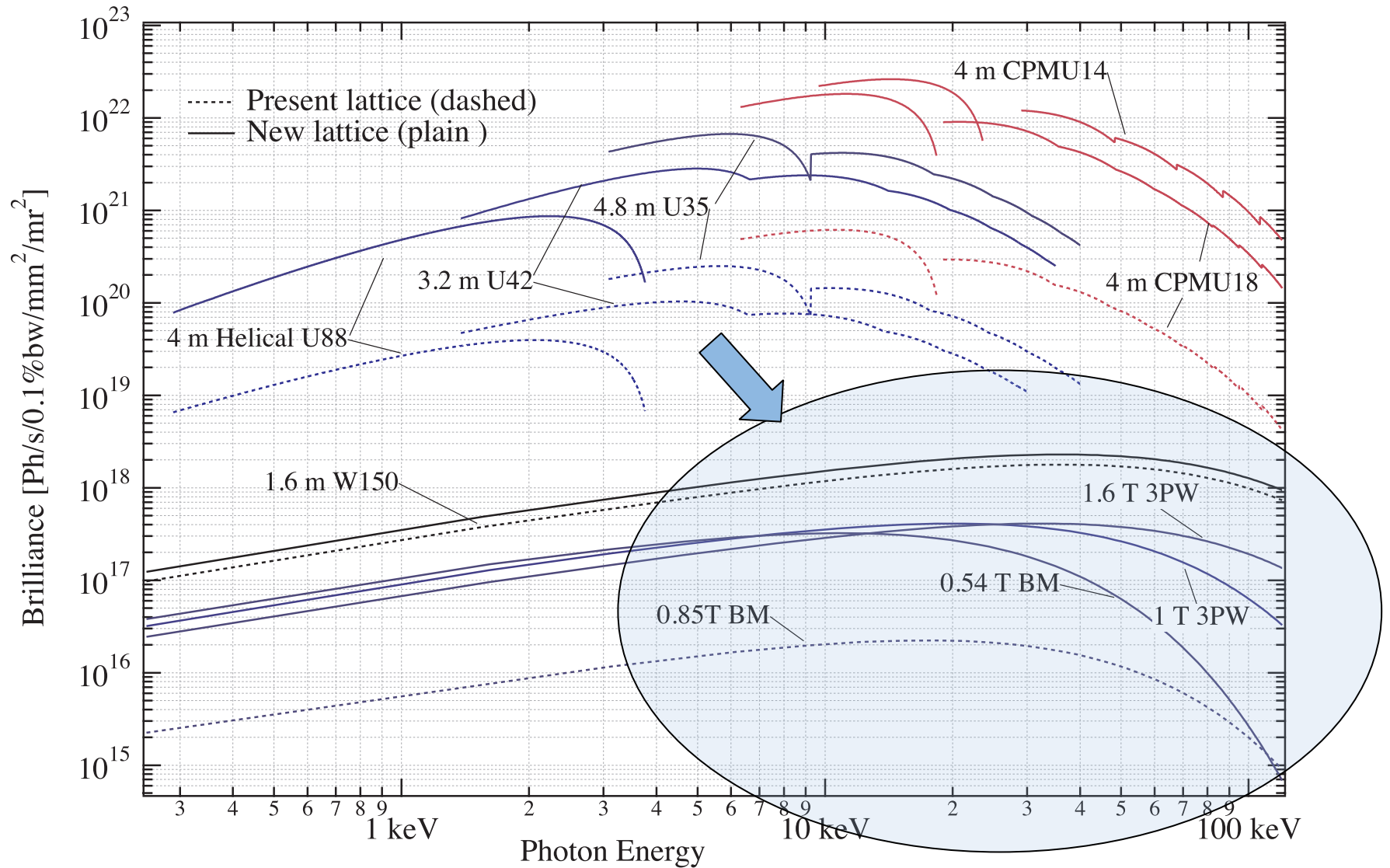
Concept used for a septum quadrupole at Hera

Can be adapted for DQs
Easier Vacuum chamber engineering

- Many Hard X-ray users on BM beamline in present high energy facilities
- General trend in MBAs is (obviously) to reduce the BM field
- DQs used as BM source points (ESRF, APS) with reduced field
 - easier engineering
 - Lower wall plug power
- Clearly conflicting with hard X-ray demand from BM beamlines
- ESRF has presently 0.85 T BM (+0.4 T short soft ends)



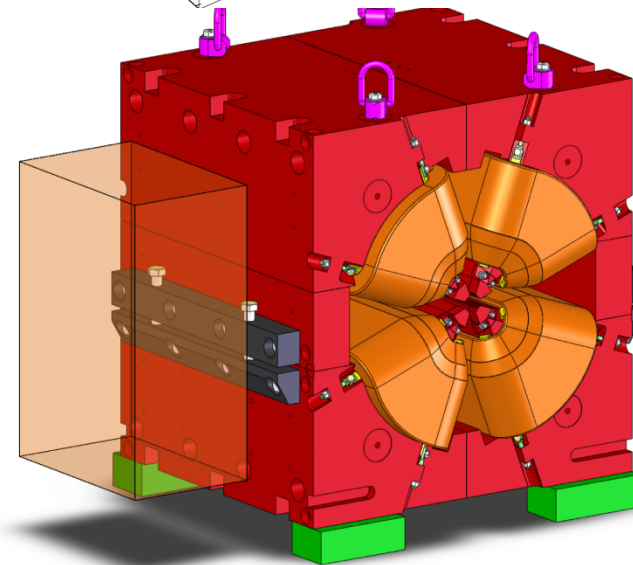
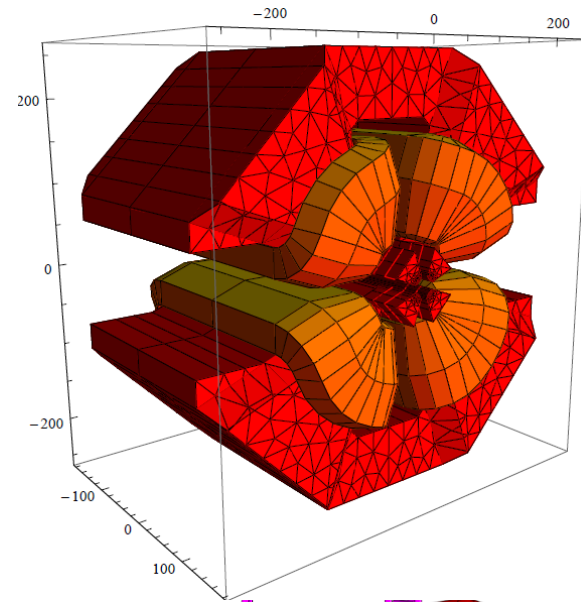
Mini-wiggler or 3 poles wiggler (3PW) or wavelength shifter
 Beamline not anymore linked to BM field
 More flexibility to BL, (Mini Insertion Device source)

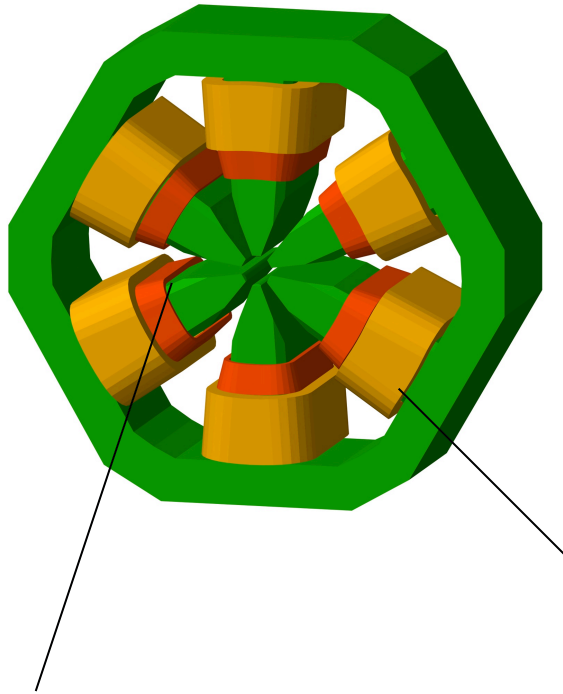


ESRF Quadrupole prototype

- High gradient QF8B
- 100 T/m
- 500 mm long
- Massive iron (ARMCO type)
- 12.5 mm bore radius
- 1.85 kW
- Close to saturation @ 100 T/m

Engineering design of QF8B quadrupole prototype





Main sextupole coil

Sextupole Parameters

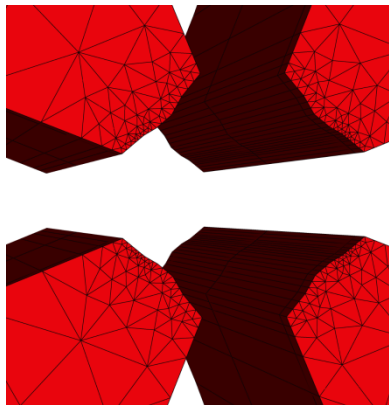
- Bore radius : 19 mm
- $B''=3200 \text{ T/mm}^2$ nominal, 4900 max.
- Iron Length: 200mm
- Outer diameter: 430mm
- Total length (iron+coils): 262 mm
- Power: 430 W @ nominal field
- Min. Vertical gap between poles: 10 mm
- Laminated iron (Fast Orbit Correction)

Corrector coil; Horizontal and vertical orbit correction, skew quadrupole correction

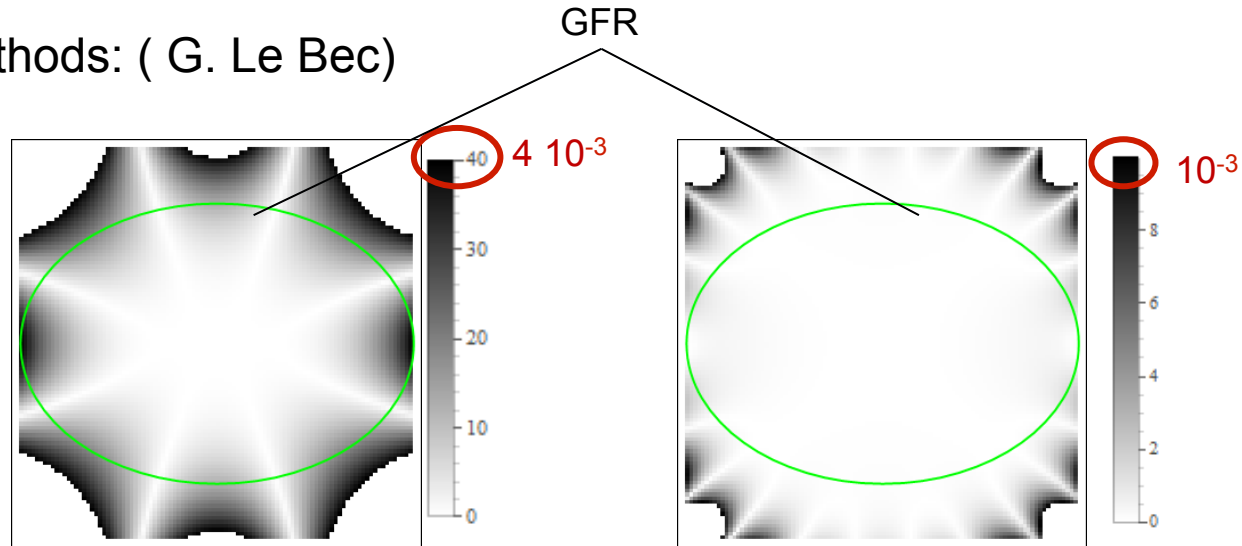
Additional version with dedicated modified yoke for photon beam stay clear (BM X-Ray source)

Improve field quality in GFR

Different (iterative) methods: (G. Le Bec)



Optimized poles for high gradient quadrupole



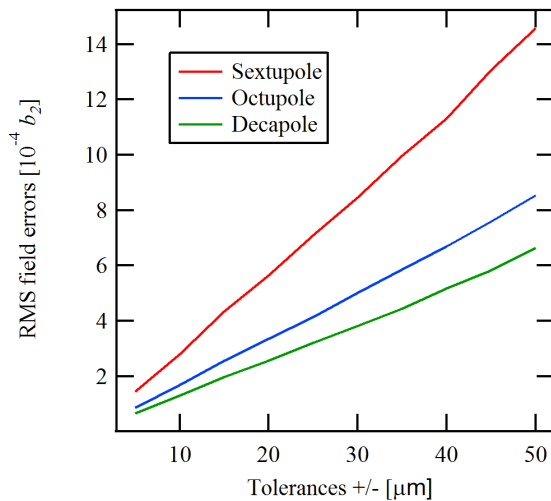
Hyperbolic profile

Modified profile

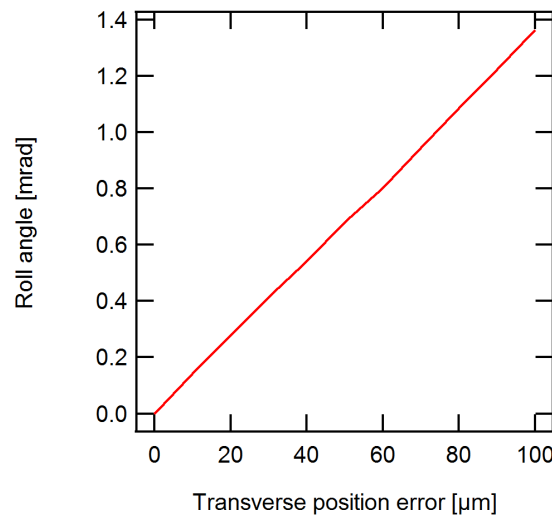
Gradient error plots (Dg/g)

Quadrupole magnet Gradient: 100 T/m
Bore radius: 12.5 mm

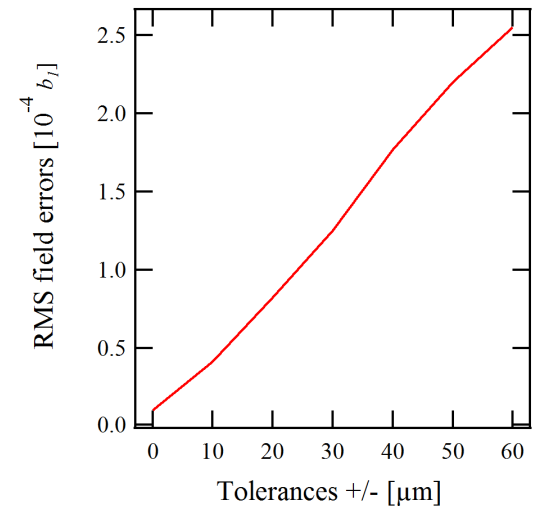
Sensitivity to random mechanical errors



Mechanical tolerances.
(Quadrupole, 100 T/m, 12.5 mm bore radius, at $r_0=7$ mm.)



Transverse misalignment.
(Quadrupole, 100 T/m, 12.5 mm bore radius, at $r_0=7$ mm.)



Mechanical tolerances.
(Dipole, 0.5T, 25 mm gap.)

Different strategies:

1- “A la MAX IV”

- Common yoke for magnets on girder
- Massive iron yoke
- Rely on precise girder machining
- Magnet alignment = mechanical alignment
- Limited effort on magnetic measurements

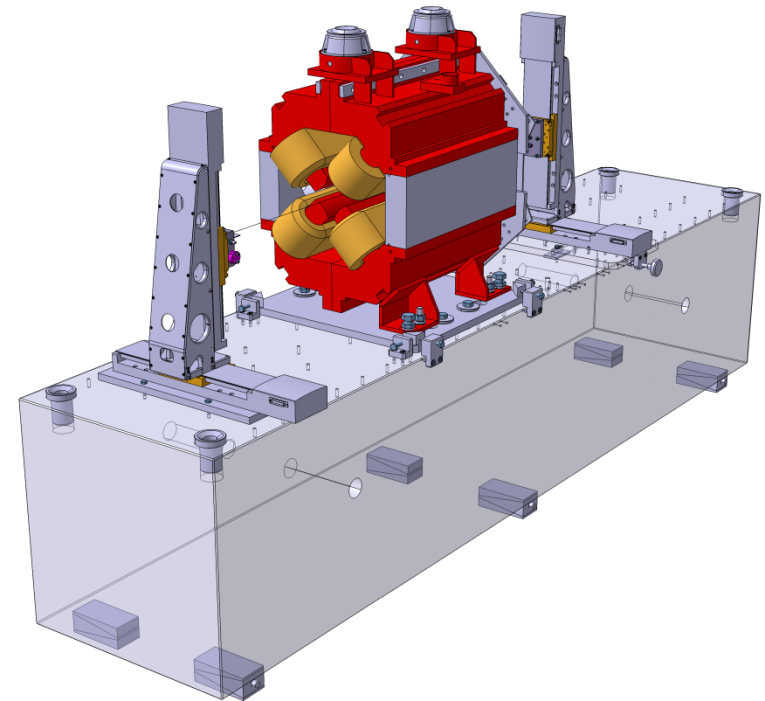
Expect outcomes very soon



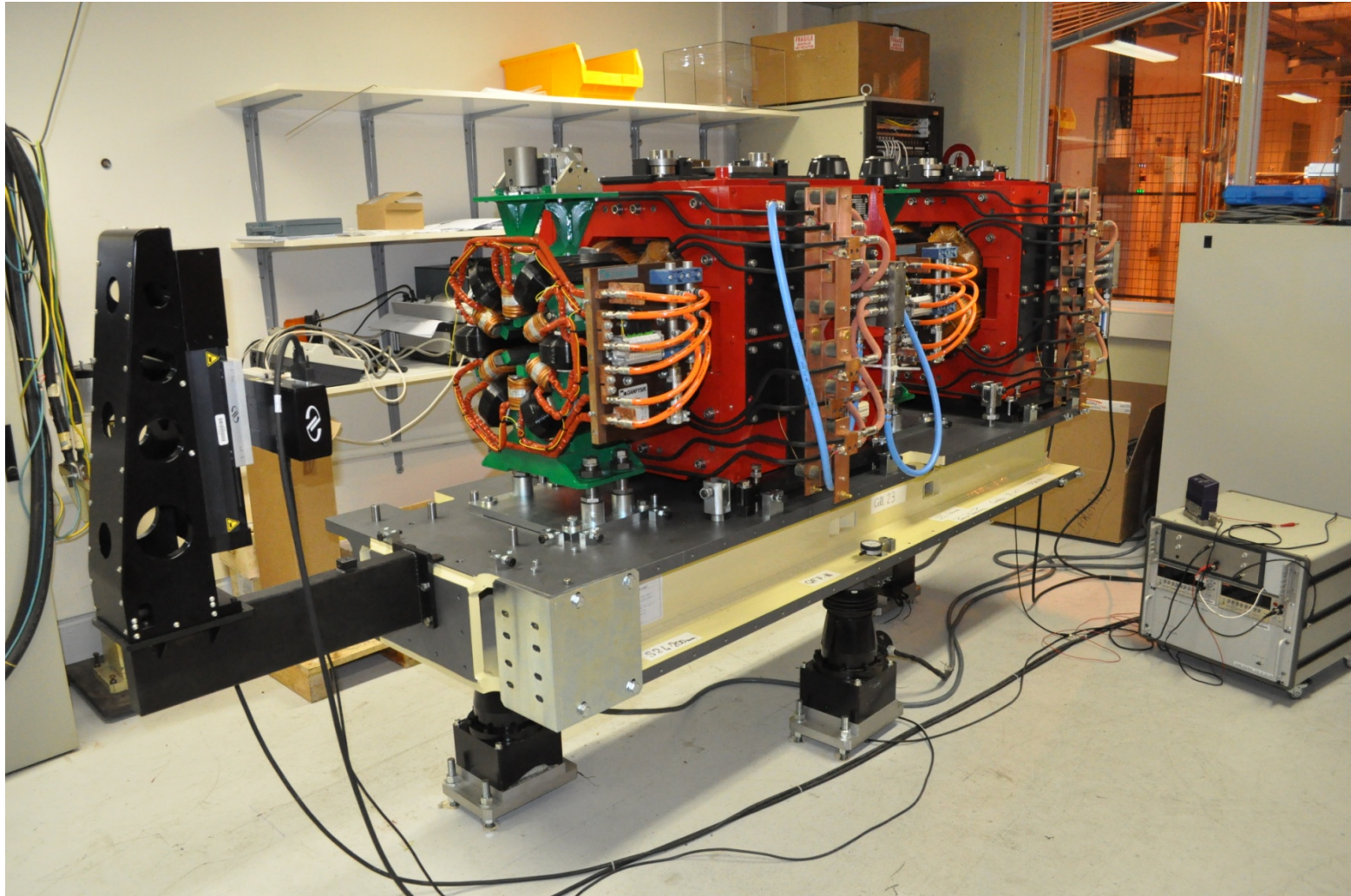
MAX IV open girder

2- Individual magnet approach

- Separated magnets
- Individual magnetic characterization
 - Multipoles analysis
 - Magnetic center
- Relative magnet alignment on girder done using stretched/vibrating wire
- Applicable to straight magnets only
- Positive experience from NSLS II & ESRF



ESRF stretched wire bench



G10 girder (cell30) equipped with the *in situ* measurement bench.

Alignment approaches (G. Le Bec)

In situ alignment

- All the magnets are aligned on a wire

$$\sigma \approx 20 \mu\text{m}$$

- Transfer to the survey monuments

$$\sigma \approx 50 \mu\text{m}$$

Classical alignment

- Magnets are measured in lab
- Survey monuments are adjusted

$$\sigma \approx 50 \mu\text{m}$$

- The magnets are aligned using the survey monuments

$$\sigma > 50 \mu\text{m}$$

- Similar results with precise spacers

Better alignment with the *in situ* method

- Alignment errors driven by the magnet position adjustment
- Will be mandatory for the future lattice high gradient magnets

1 Magnet Design

- **Aggressive quadrupoles & sextupoles in DLSRs**
 - Small magnet aperture
 - Field quality seems reachable
 - Quadrupoles~ close to saturation, still some margin on sextupoles
 - Vertical pole gap can be a limiting factor for field quality
 - Required mechanical tolerances may be difficult to reach (cost)
- **New types of Bending Magnets**
 - DLs
 - Feasible without doubt
 - High gradient DQs
 - X-ray source points for BM beamlines
 - Trade off between high gradient & high field
- **Prototyping will be essential**
- **No show stopper for the time being**

2 Magnetic measurements/alignments

- Recent R&D in magnetic measurements definitely helpful
 - Stretched wire
 - Vibrating wire
- Further work needed for curved magnets
- Alignment
 - Rely on machining tolerance (Max IV)
 - In situ alignment on girder using wire