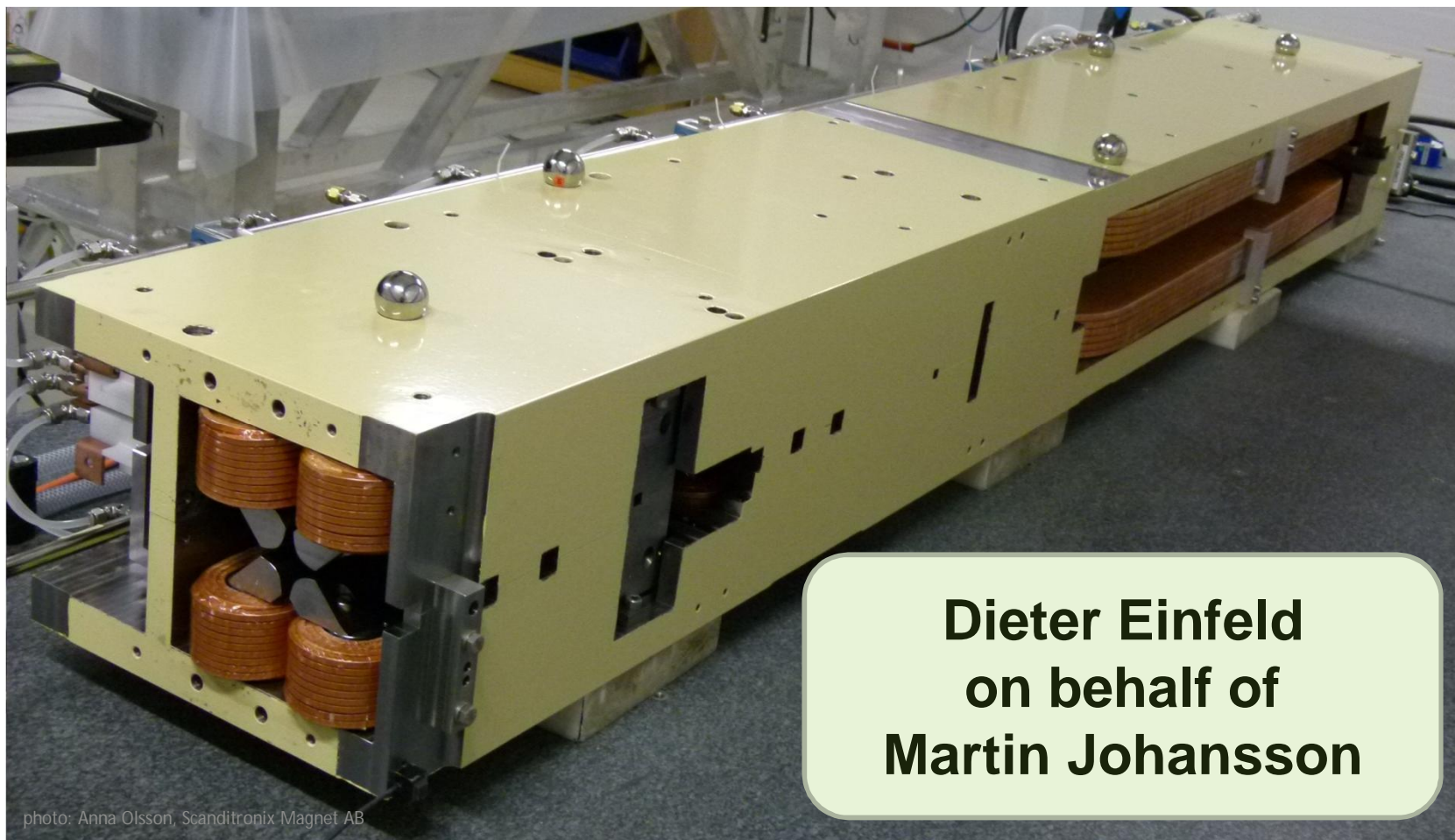


# *Magnets for MAX IV*



**Dieter Einfeld  
on behalf of  
Martin Johansson**

# *Magnets for MAX IV*

**Contents:**

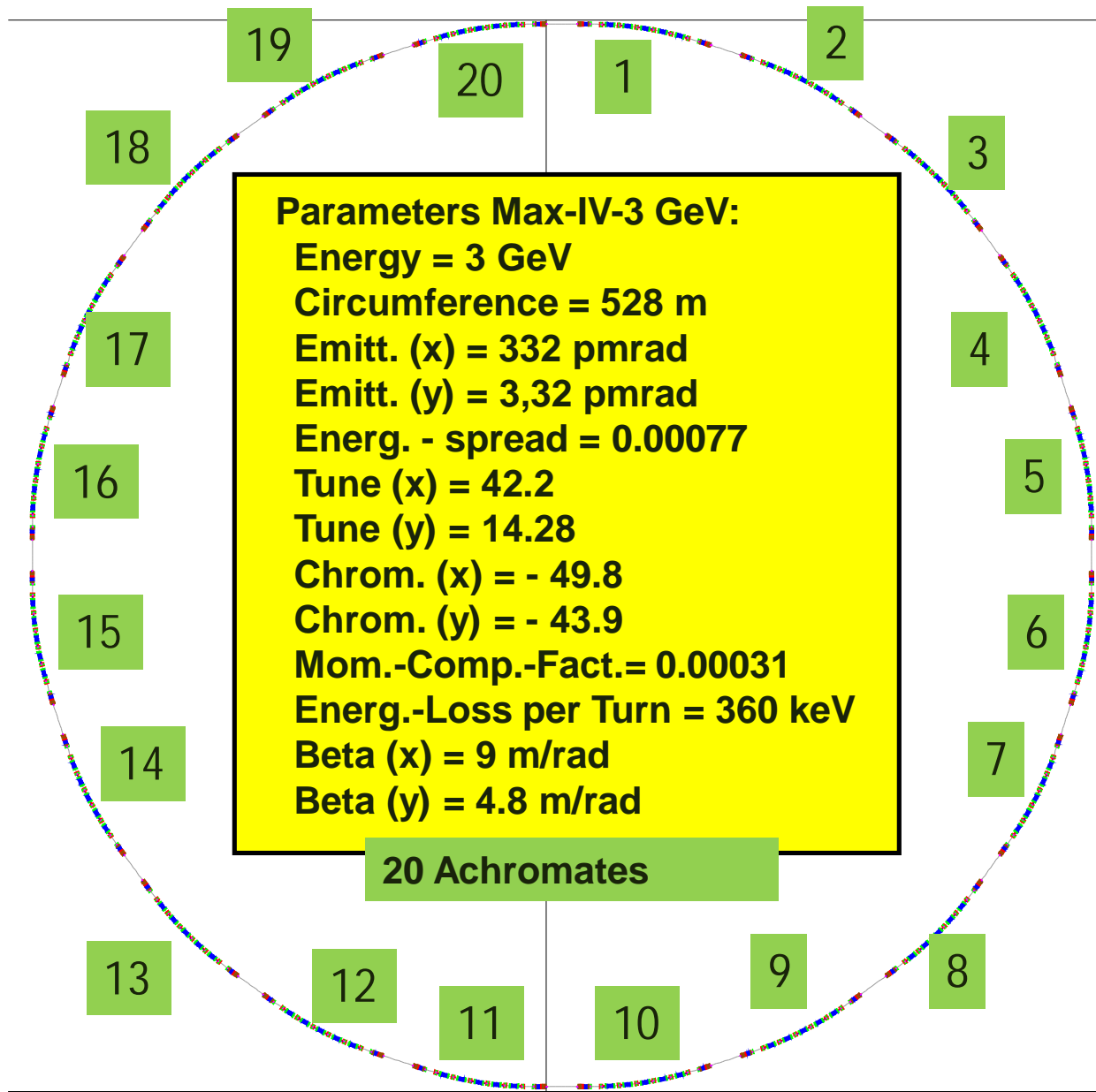
**1.) Magnet Specifications**

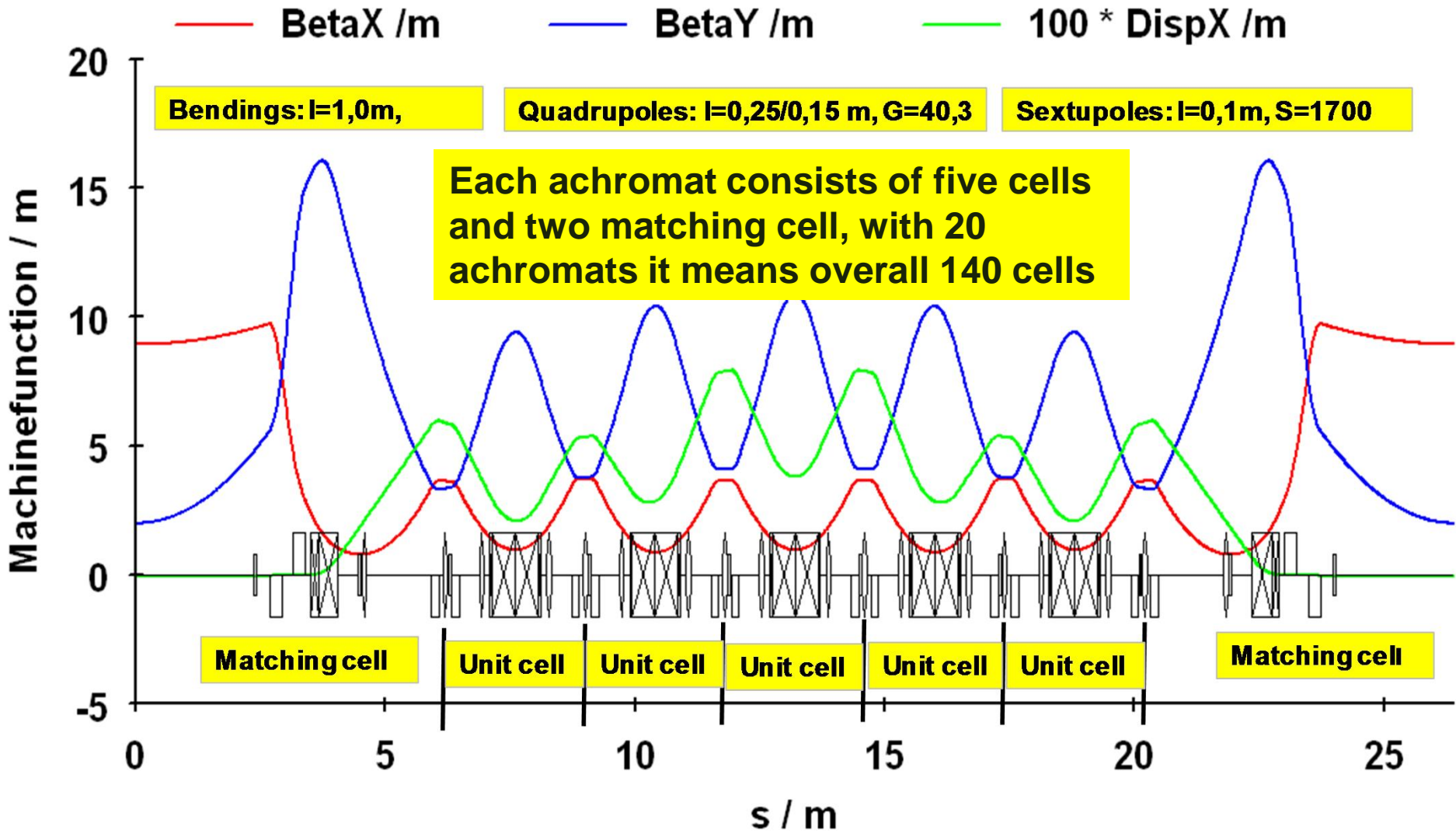
**2.) Design**

**3.) Manufacturing**

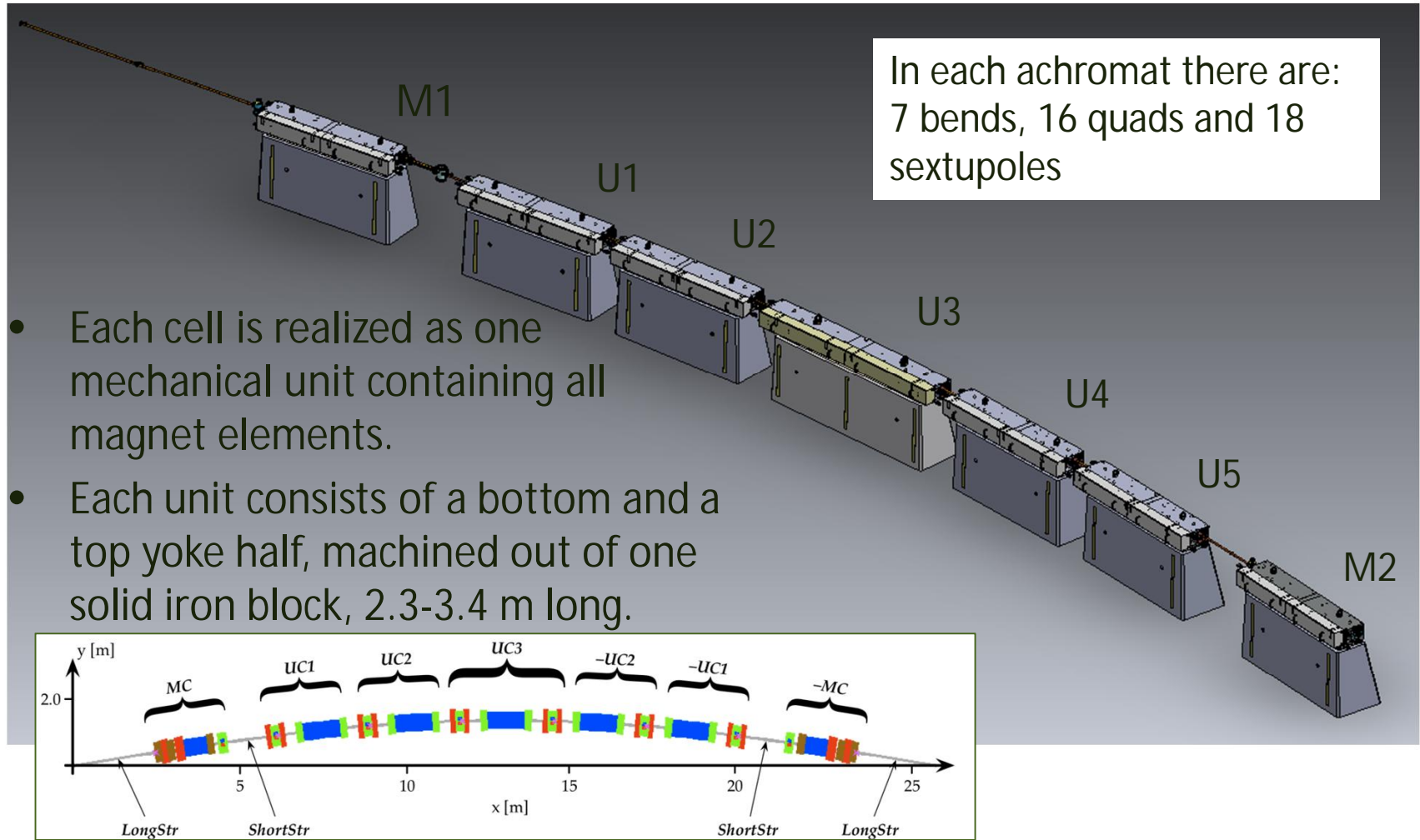
**4.) Results**

photo: Anna Olsson, Scanditronix Magnet AB



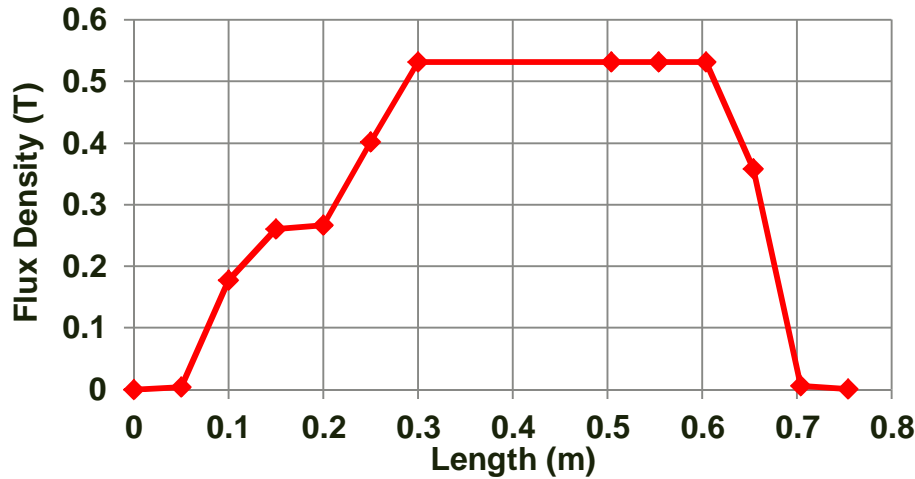


# Achromat 3D cad assembly:

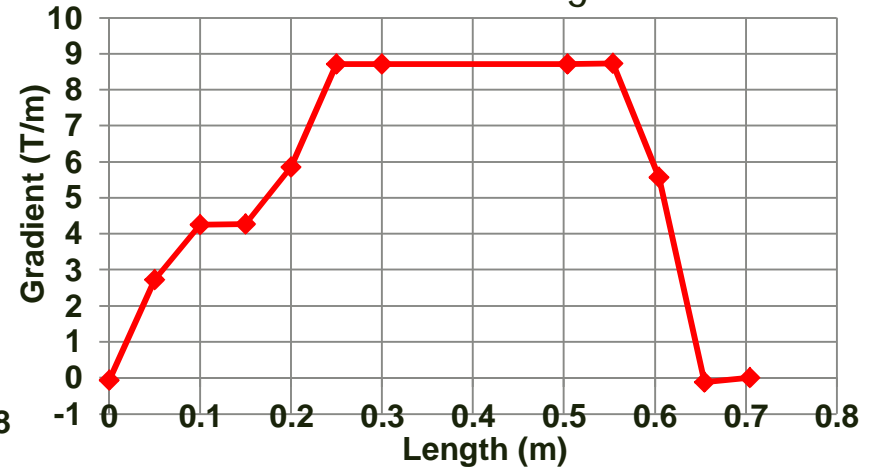


# Bendings: Field and Gradient

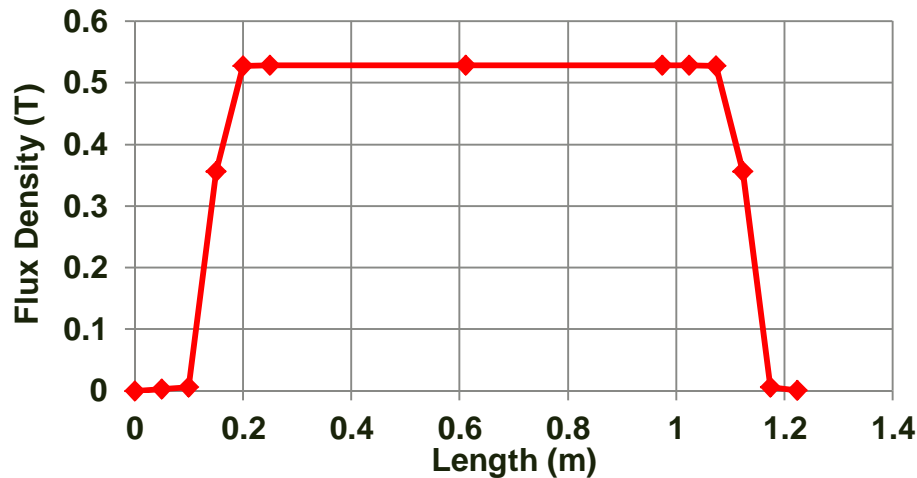
## Field of matching Bend



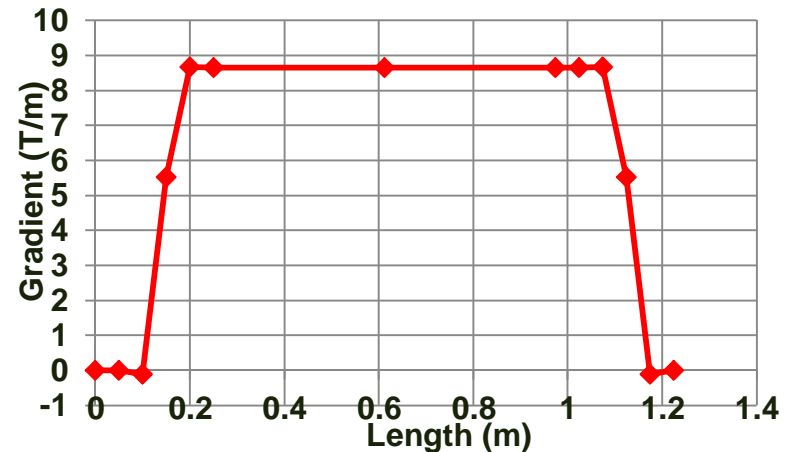
## Gradient of matching Bend



## Field of unit Bend

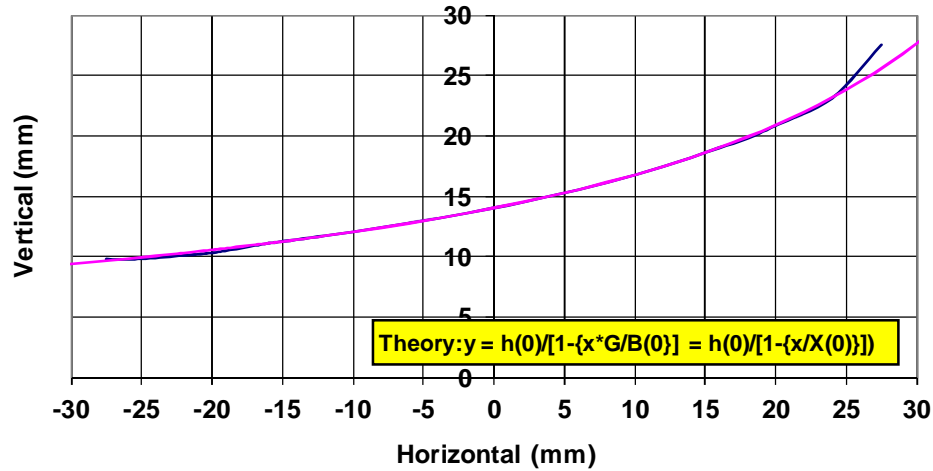


## Gradient of unit Bend



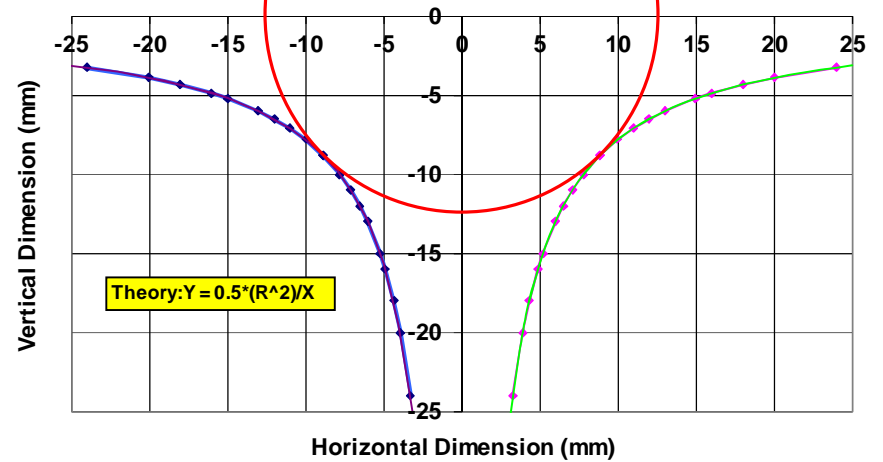
### DIP Pole Profile

— DIP — Theory B(0)=0.524,G(0)=8.6205



### Pole Profile SQFo

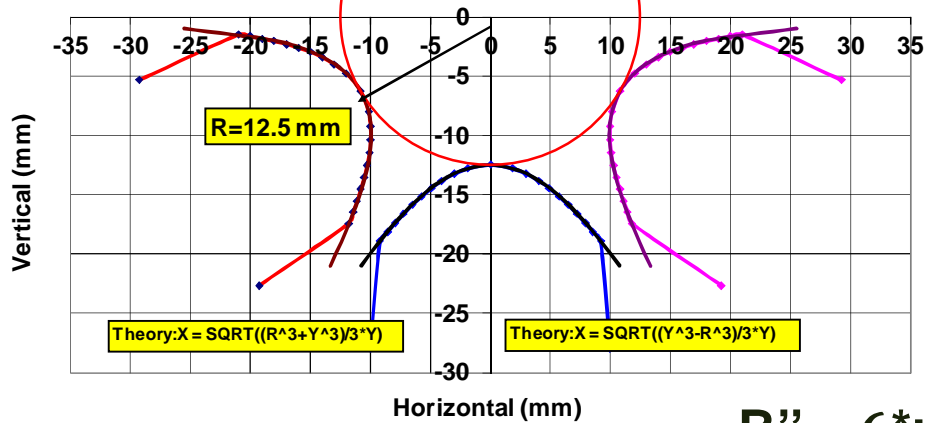
— Left Pole — Right Pole — Theory-I — Theory-II



$$G = 2 * \mu(0) * N * I / (R^2)$$

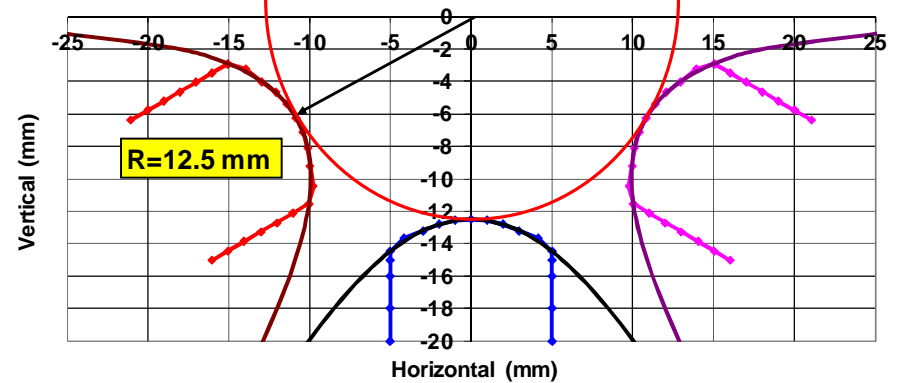
### Sfm Pole Profile

— Left Pole — Right Pole — Center Pole — Theory I — Theory II — Theory III



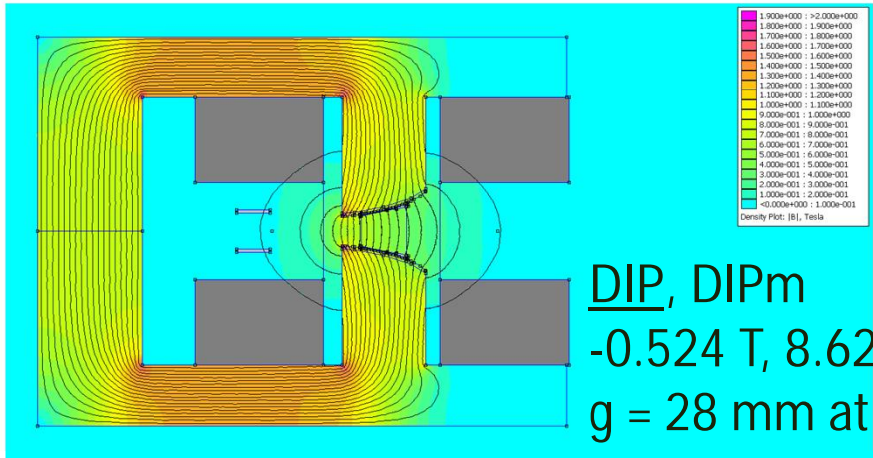
### SDend Pole Profile

— Left Pole — Right Pole — Center Pole — Theory I — Theory II — Theory III

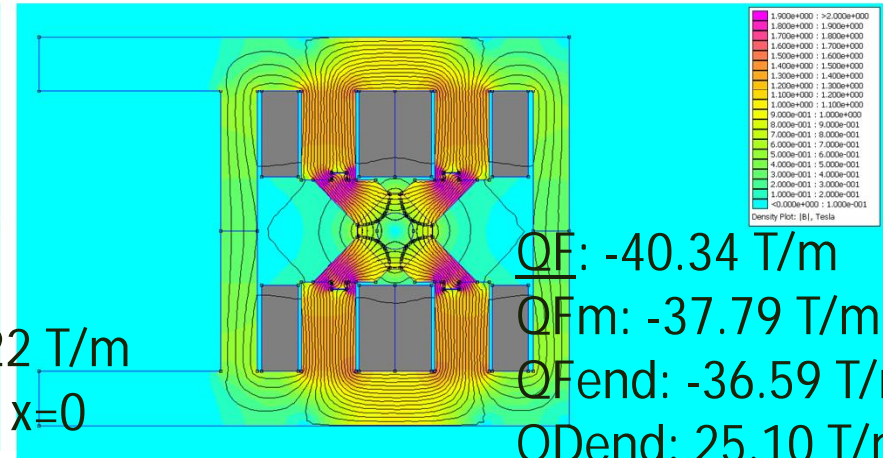


$$B'' = 6 * \mu(0) * N * I / (R^3)$$

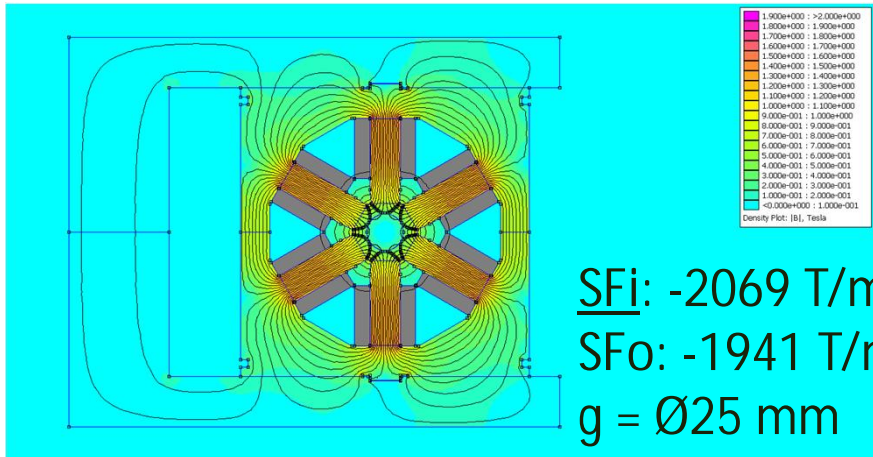
# magnet elements:



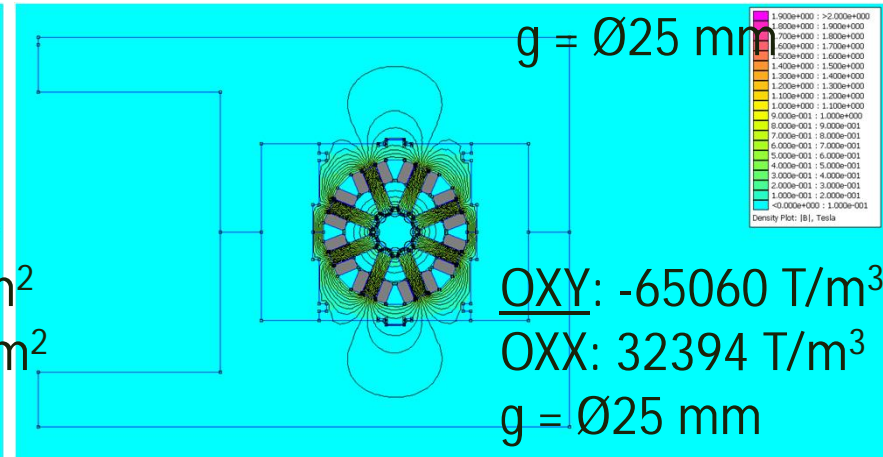
DIP, DIPm  
 $-0.524\text{ T}$ ,  $8.622\text{ T/m}$   
 $g = 28\text{ mm}$  at  $x=0$



QF:  $-40.34\text{ T/m}$   
 QFm:  $-37.79\text{ T/m}$   
 QFend:  $-36.59\text{ T/m}$   
 QDend:  $25.10\text{ T/m}$



SFi:  $-2069\text{ T/m}^2$   
 SFo:  $-1941\text{ T/m}^2$   
 $g = \text{Ø}25\text{ mm}$



OXY:  $-65060\text{ T/m}^3$   
 OXX:  $32394\text{ T/m}^3$   
 $g = \text{Ø}25\text{ mm}$

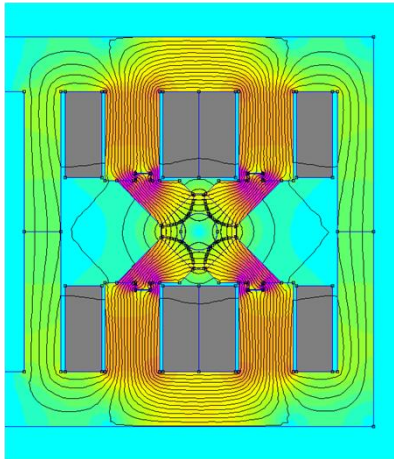
... + SFm, SD, SDend ( $g = \text{Ø}25\text{ mm}$ ), OYY ( $g = \text{Ø}36\text{ mm}$ ) and corr h/v ( $g = 25\text{ mm}$ )



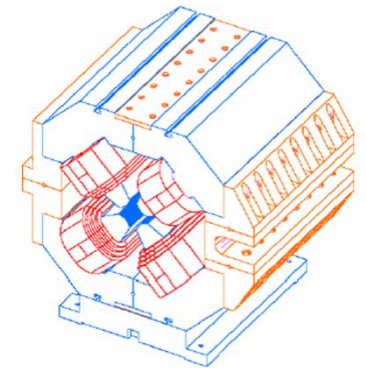
## Magnets in Max-IV 3 GeV (Dec. 2012)

Section:	Magnets	Length	B / k / m	Gr. / B"	Current	N*I	B(pole)
MC1	QFend	0.25	3.654	36.570	58.3	2273.7	0.457
	QDend	0.25	-2.504	-25.058	40	1560	0.314
	DIP (soft)	0.15	0.377	5.837	395	11850	0.266
	Dip (hard)	0.4	0.513	8.608	395	11850	0.532
	SDend	0.1	-134.000	-2682.305	53.45	694.85	0.210
U1	QFm	0.15	3.774	37.772	60.25	2349.75	0.472
	SFm	0.1	160.000	3202.752	63.82	829.66	0.250
	QFm	0.15	3.774	37.772	60.25	2349.75	0.472
	SD	0.1	-116.625	-2334.506	54.98	604.78	0.182
	DIP	1	0.524	8.608	681	36774	0.528
	SD	0.1	-116.625	-2334.506	54.98	604.78	0.182
U2	QF	0.15	-4.030	-40.335	64.3	2507.7	0.504
	SFo	0.1	170.000	3402.924	58.76	881.4	0.266
	QF	0.15	-4.030	-40.335	64.3	2507.7	0.504
	SD	0.1	-116.625	-2334.506	54.98	604.78	0.182
	DIP			0.000	681	36774	0.528
	SD	0.1	-116.625	-2334.506	54.98	604.78	0.182
U3	QF	0.15	4.030	40.335	64.3	2507.7	0.504
	SFi	0.1	207.412	4151.807	71.7	1075.5	0.324
	QF	0.15	4.030	40.335	64.3	2507.7	0.504
	SD	0.1	-116.625	-2334.506	54.98	604.78	0.182
	DIP			0.000	681	36774	0.528
	SD	0.1	-116.625	-2334.506	54.98	604.78	0.182
	QF	0.15	4.030	40.335	64.3	2507.7	0.504
	SFi	0.1	207.412	4151.807	71.7	1075.5	0.324
	QF	0.15	4.030	40.335	64.3	2507.7	0.504

# Comparison between ALBA and MAX IV Quads



		MAX IV	ALBA
Gradient	(T/m)	40.24	20.1
Length	(m)	0.15	0.31
Grad.* length	(T)	6.04	6.23
Bore radius	(mm)	12.5	30.5
B(pole)	(T)	0.5	0.61
Turns per coil		39	46
Current	(A)	72.3	161
Power	(W)	250	1670



$$G = 2 * \mu(0) * N * I / (R^2)$$

# MAX IV magnet design

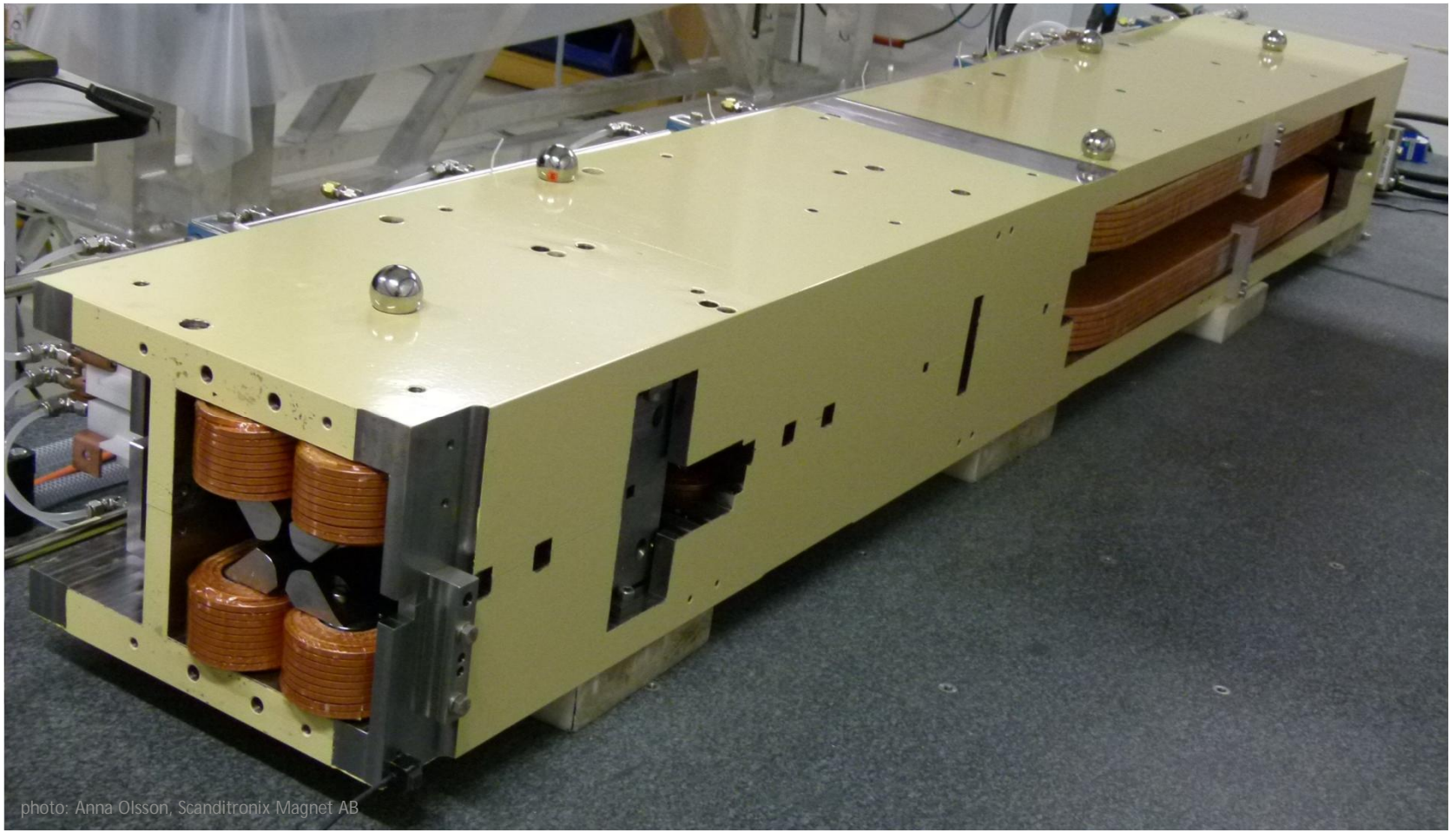


photo: Anna Olsson, Scanditronix Magnet AB



**Iron blocks  
delivered to  
Max-Lab**



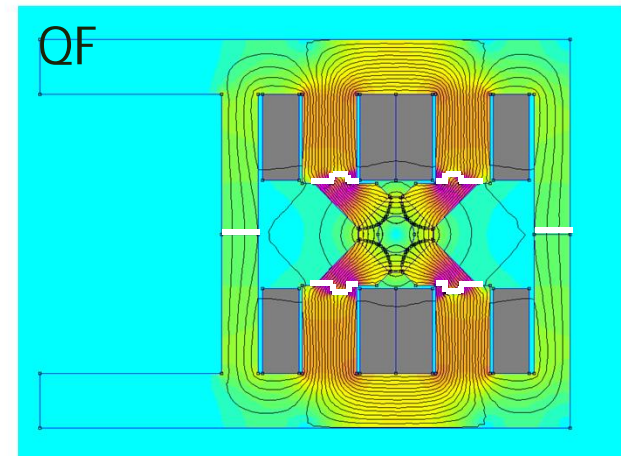
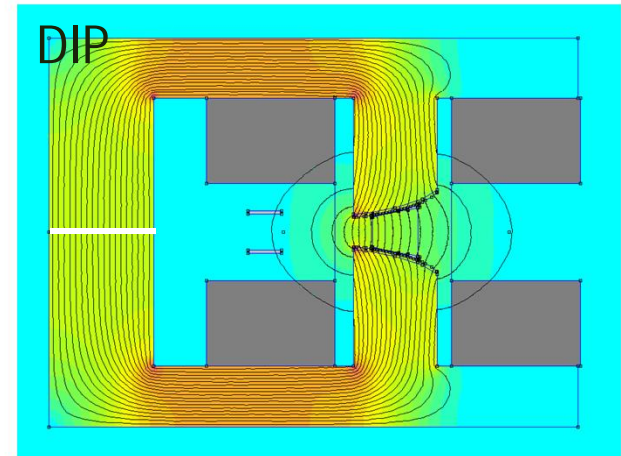
# why the magnet block concept?

As opposed to standalone magnets not sharing a common return yoke...

- First of all, separate magnets on individual adjustment stands were never considered, because
  - we assumed that optical alignment would be less accurate between consecutive elements.
  - given the small footprint of our magnet elements, designing adjustment stands stiff enough to give the same level of vibration stability would have been difficult.
- So, from the perspectives of alignment and vibration stability, we were looking at a solution with several consecutive magnet elements in the same mechanical unit.

# why the magnet block concept?

- DIP and QF cross sections →
- Separate magnets on a girder requires one more mating surface, decreasing the alignment accuracy. Therefore the magnet block concept.
- Expected rms alignment as sum of squares of parts,  $x, y = \pm 0.016, \pm 0.020$  for dipoles,  $= \pm 0.018, \pm 0.021$  for quads,  $= \pm 0.023, \pm 0.025$  for quads, with pessimistic assumption each part at max tolerance.
- Also, it is easier to achieve good vibrational stability with the magnet block concept. Lowest eigenfrequency  $\approx 90$  Hz for MAX IV, vs  $\approx 30$  Hz for MAX II.

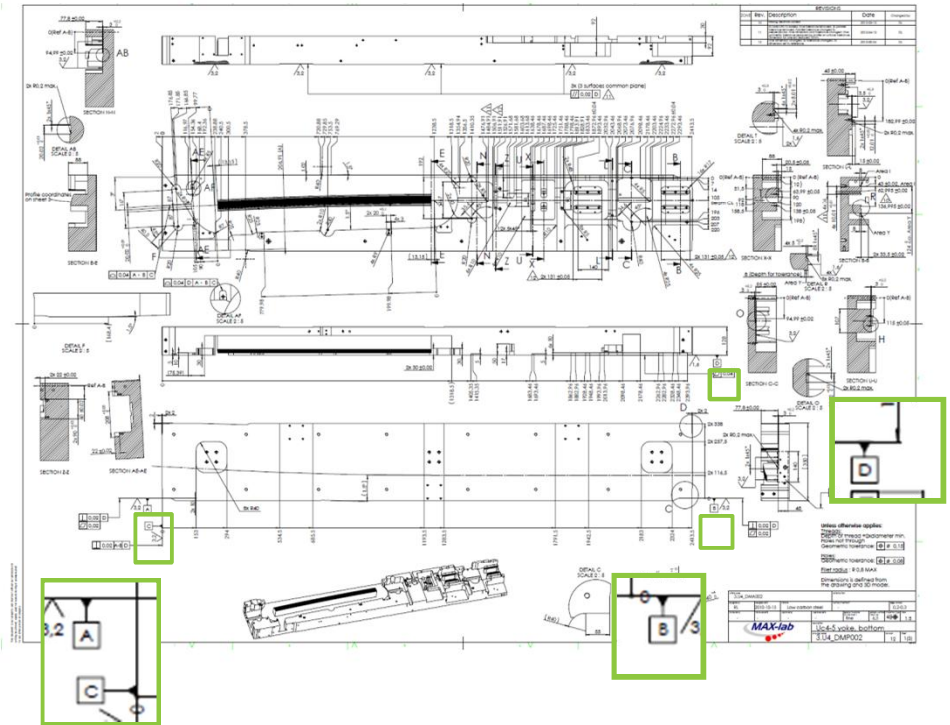


# why the magnet block concept?

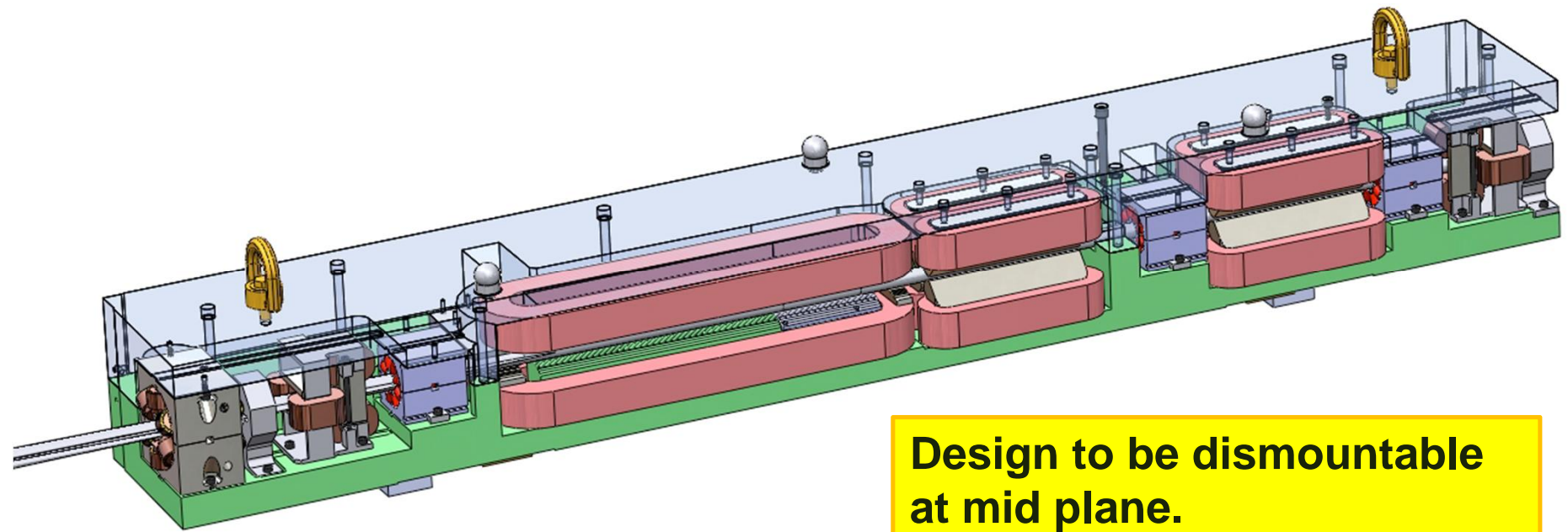
- At MAX IV, we typically want to subcontract as much work as possible to industry, minimizing the internal personnel need.
- We therefore chose an alignment concept based on mechanical tolerances over field meas. believing this is easier to subcontract to industry.

# specification

- Suppliers deliver magnet blocks fully assembled and wired, ready to put directly in ring tunnel and connect ps and water.
- Suppliers are responsible for mechanical tolerances on parts.
- MAX IV is responsible for magnetic design.
- Mechanical tolerances on the yoke bottom and top pieces are defined relative to reference planes A, B, C and D.
- Dipole surface and quad/6pole/8pole guiding surfaces have  $\pm 0.02$  mm tolerance relative to D, A-B and C.
- Suppliers perform field measurements of all magnet elements to MAX IV instructions.







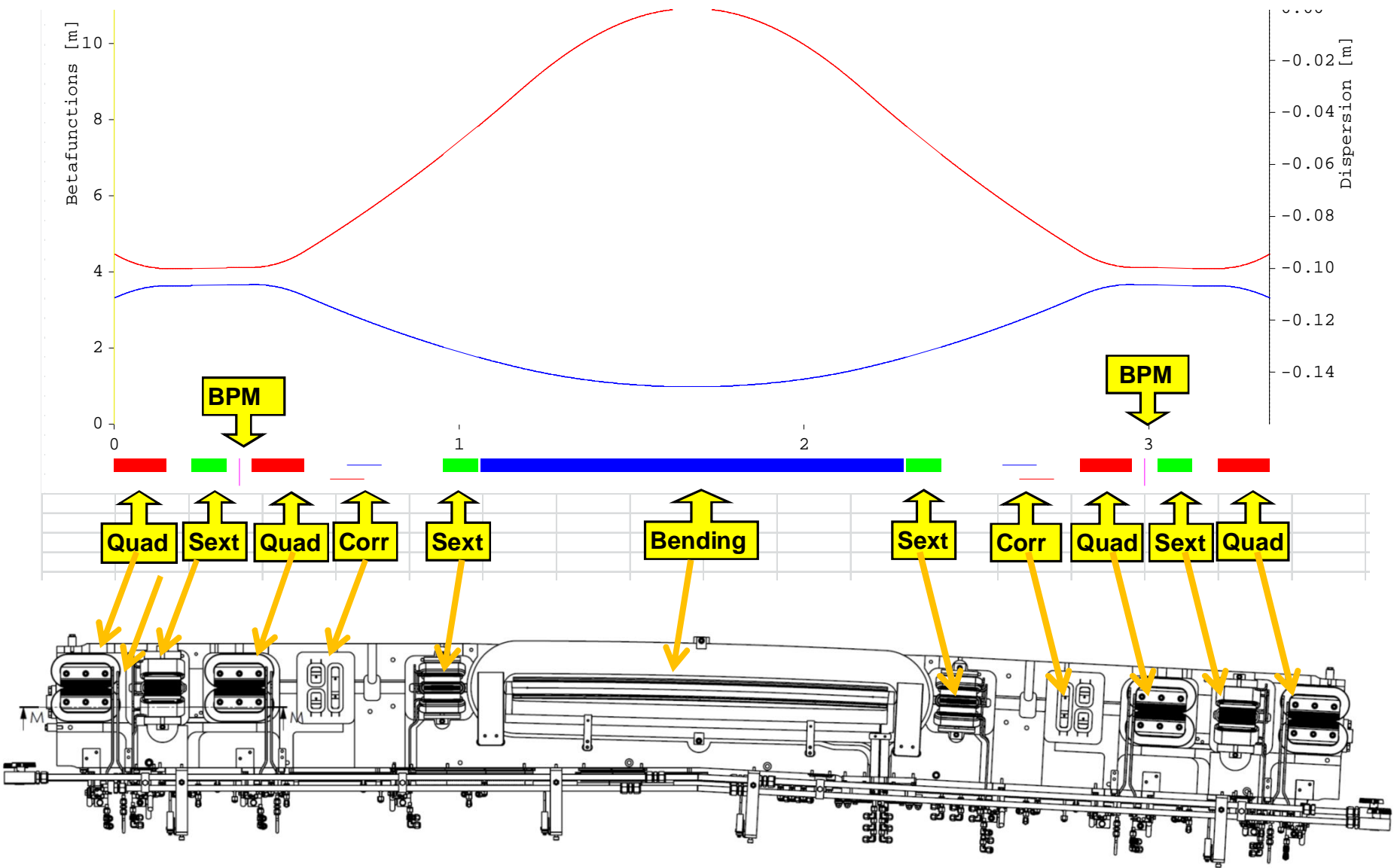
**Each cell is realized as one mechanical unit with several magnet elements.**

**Design to be dismountable at mid plane.**

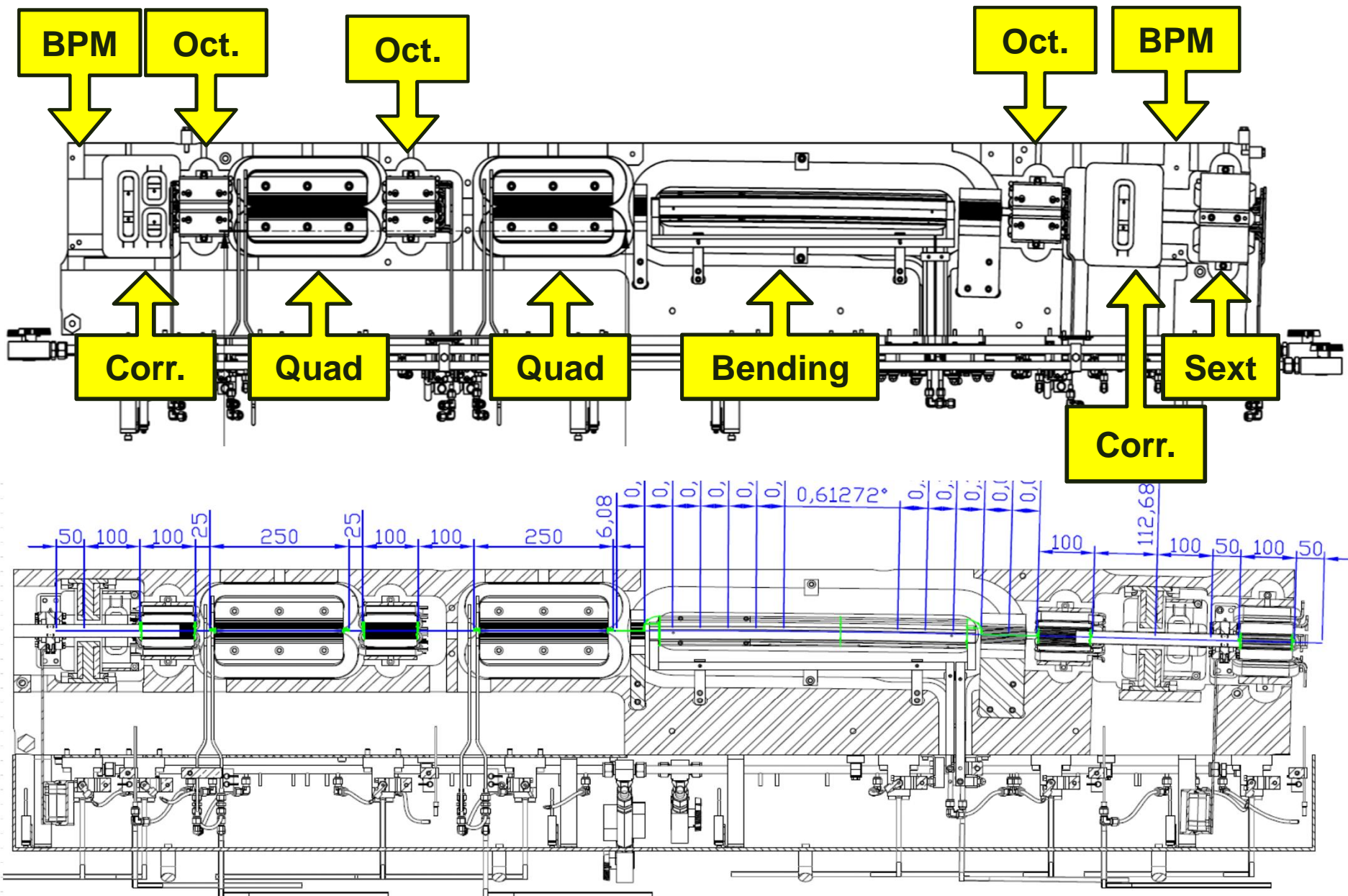
**Coils can be exchanged without breaking the vacuum.**

**Magnets connected to the same PS can be shunted to the same strength.**

# MAX IV: Unit Cell



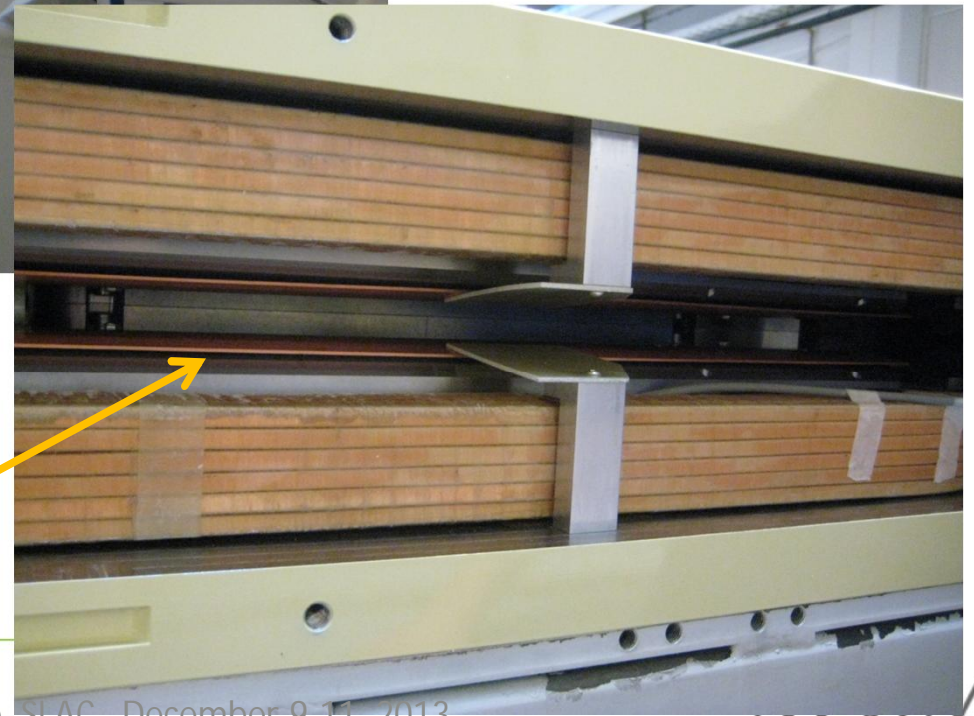
# MAX IV: Matching Cell



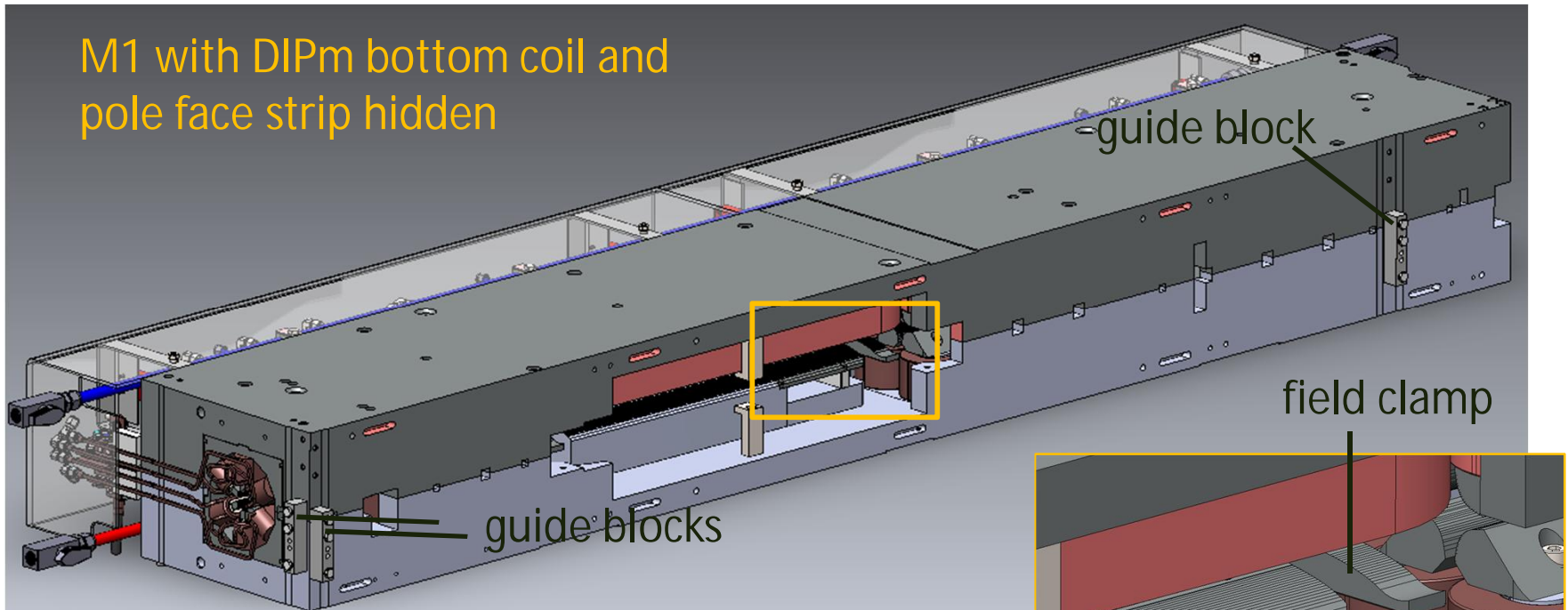


**The magnet block for UC3 with the openings to make Hall probe measurements**

**The bending magnets have pole face windings to change the gradient by  $\pm 4\%$**

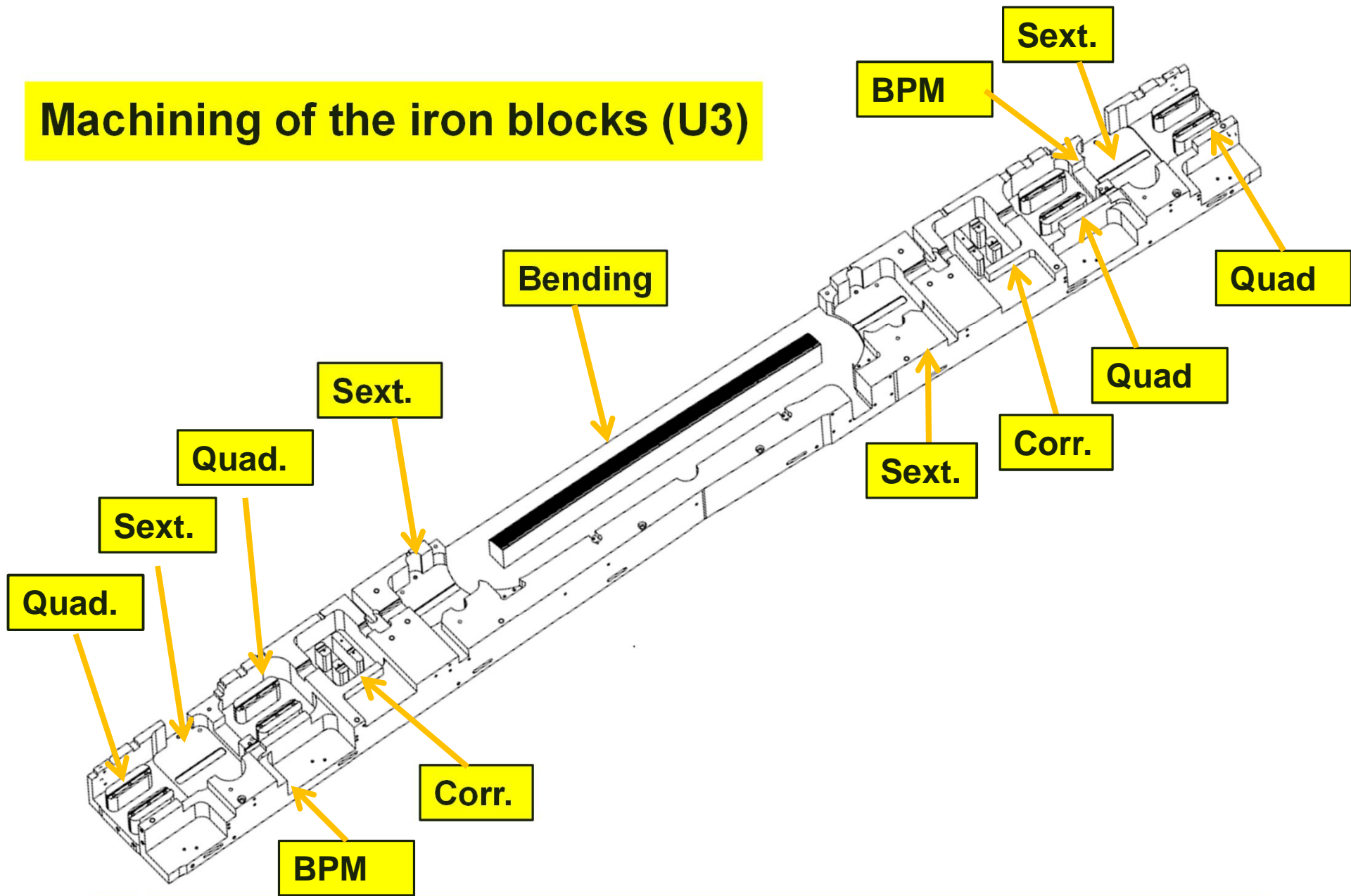


# more details:

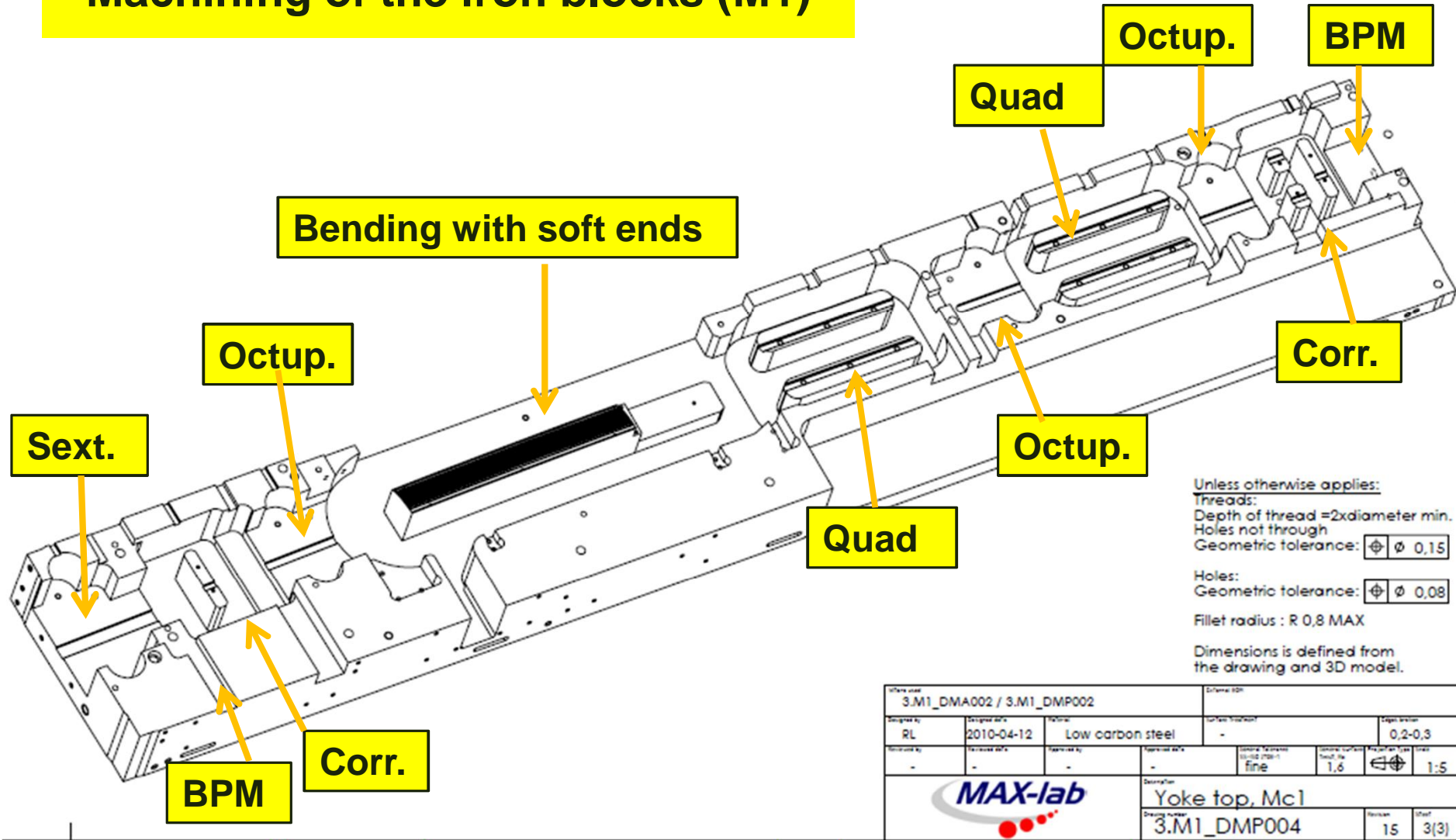


- Top half aligned to bottom half by 3 guiding blocks on bottom + top outer reference surfaces.
- Field clamps reduce the dipole fringe field distribution sensitivity to coil shape.
- M1/M2 DIPm soft end reduces thermal load to the long straight.

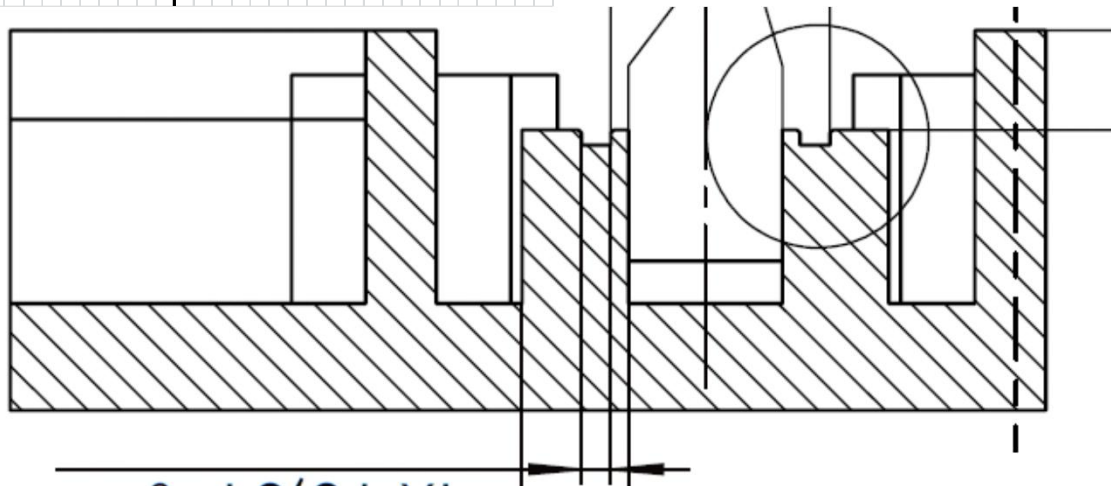
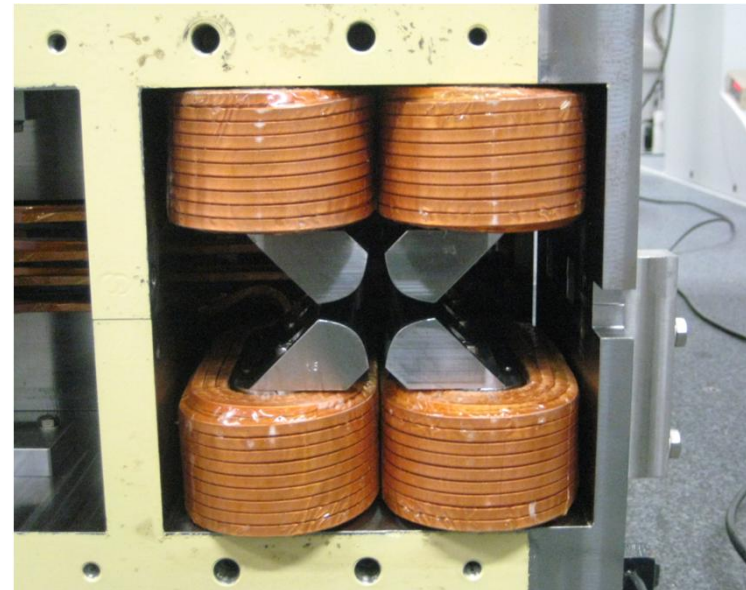
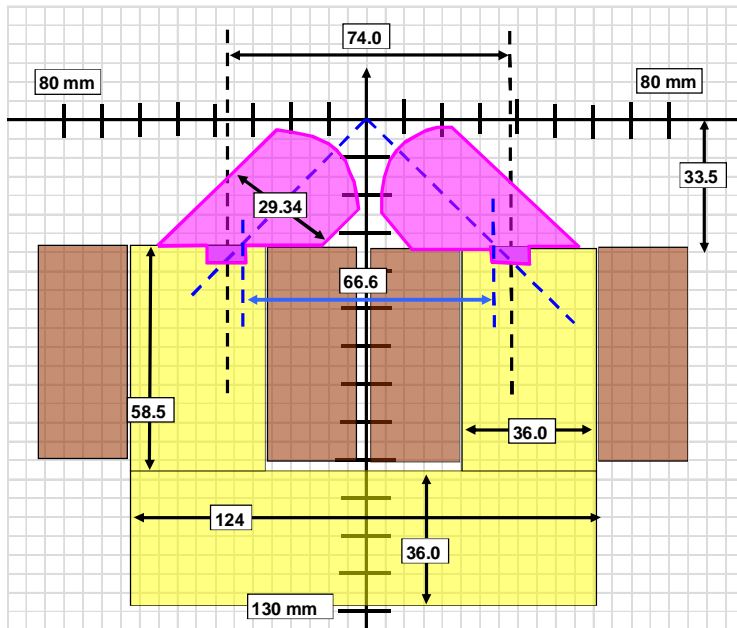
# Machining of the iron blocks (U3)



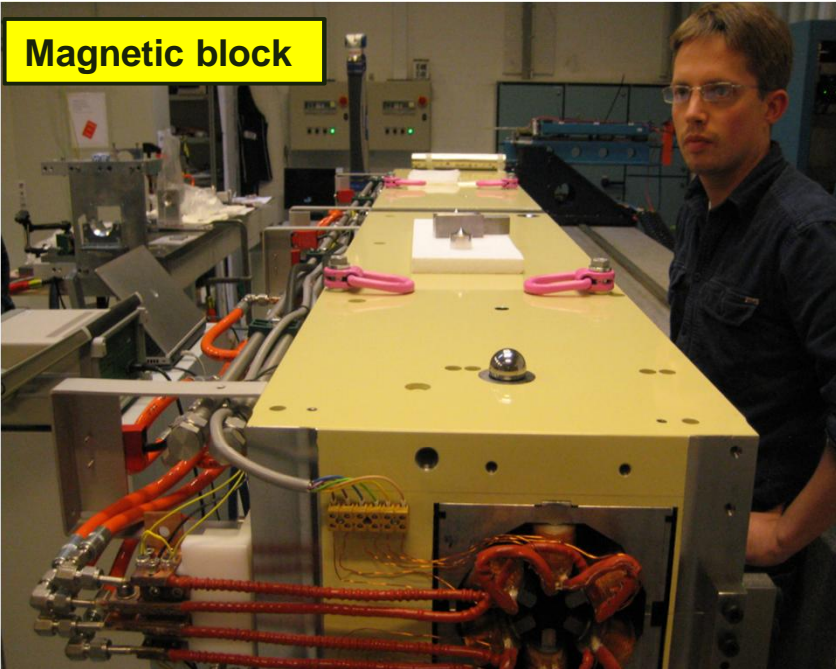
# Machining of the iron blocks (M1)



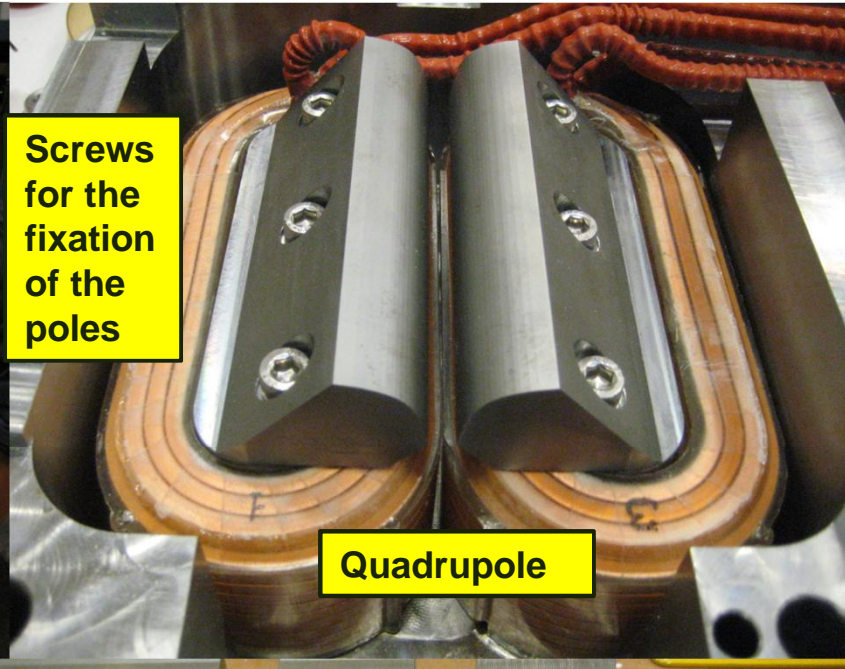
# Machining of the Quadrupoles





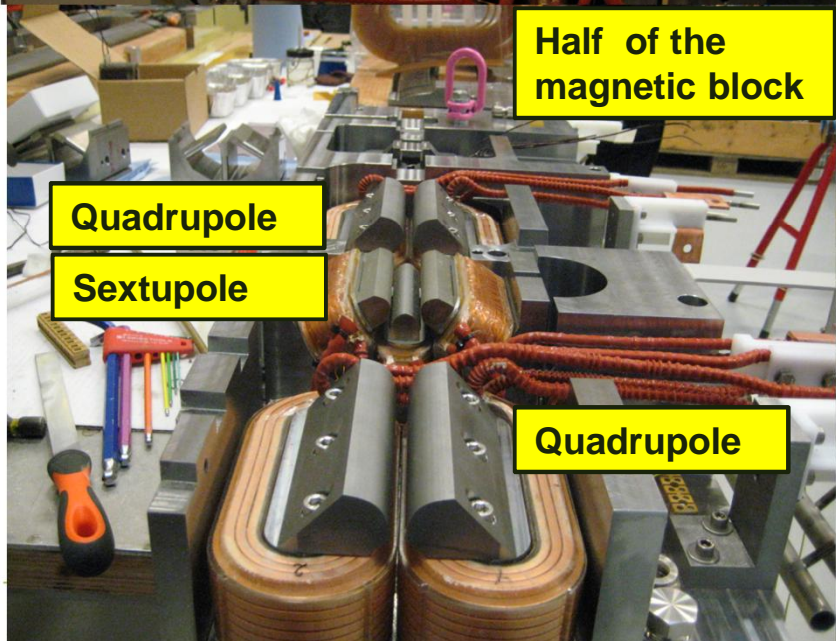


**Magnetic block**



**Screws for the fixation of the poles**

**Quadrupole**

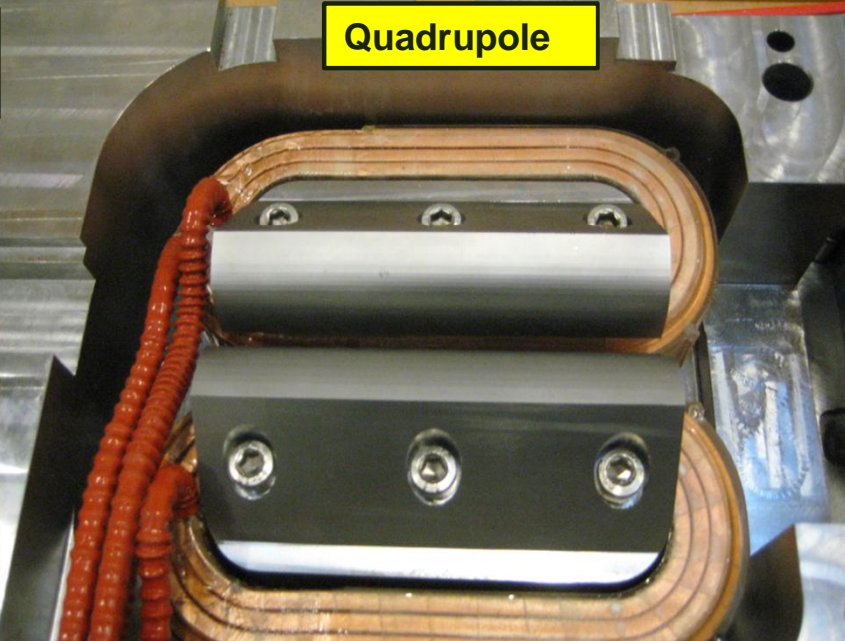


**Half of the magnetic block**

**Quadrupole**

**Sextupole**

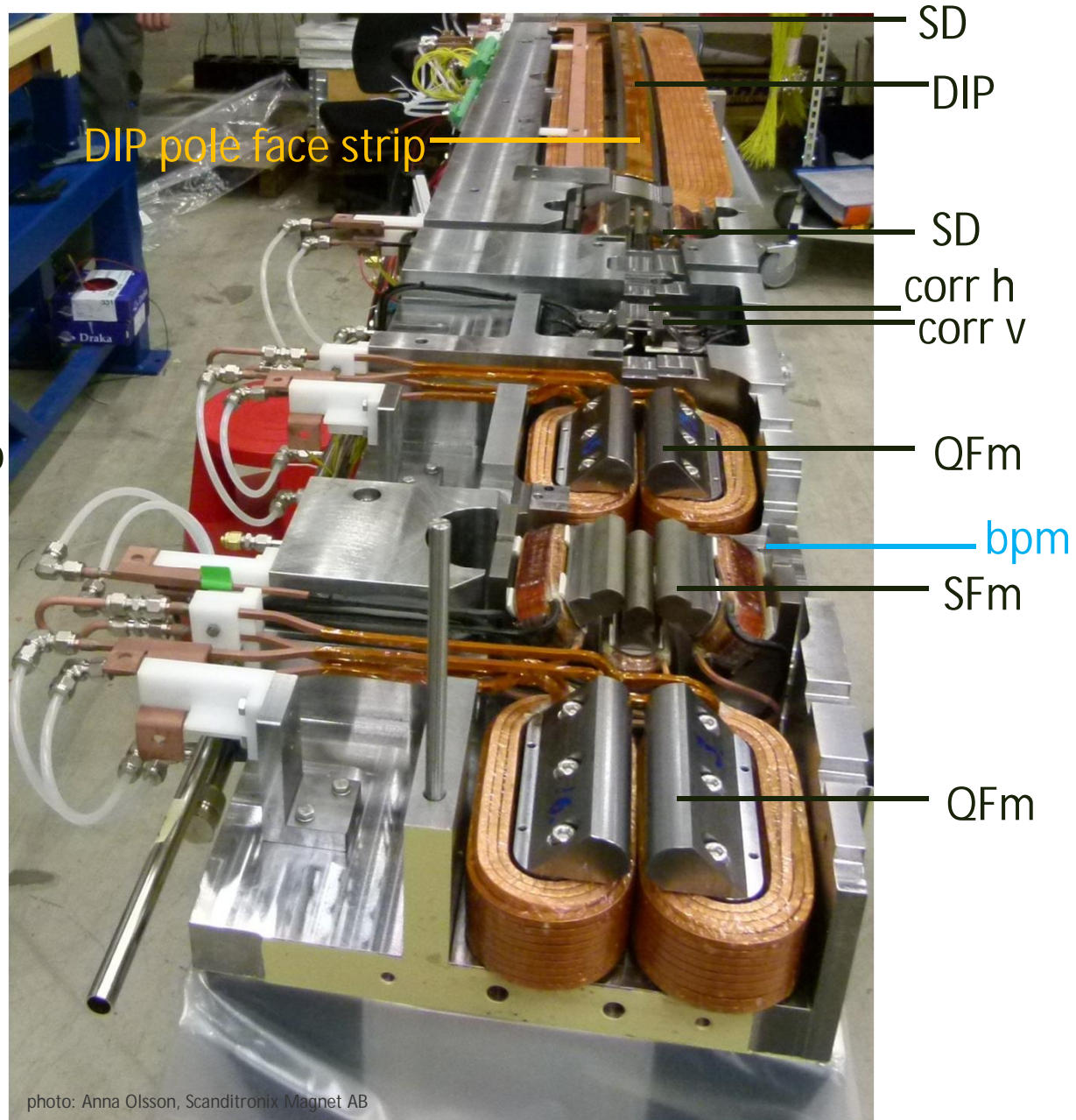
**Quadrupole**



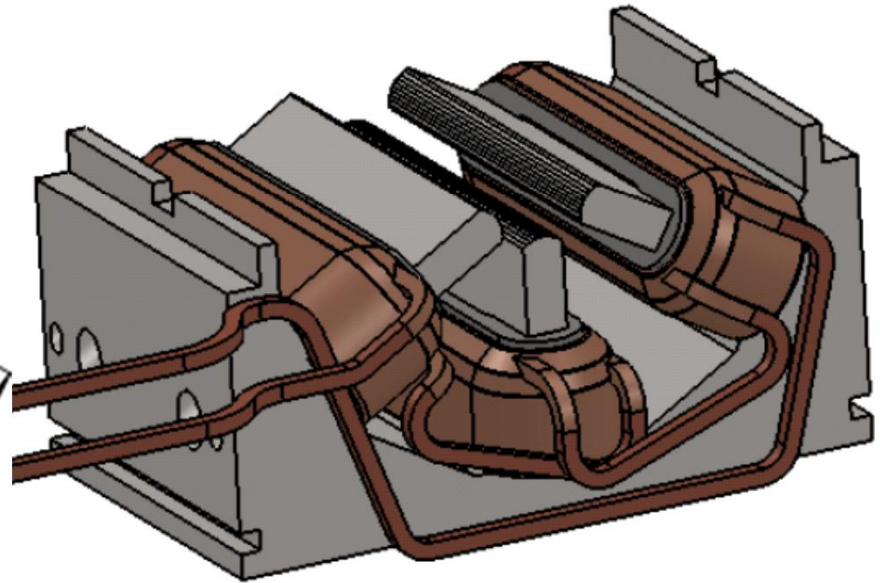
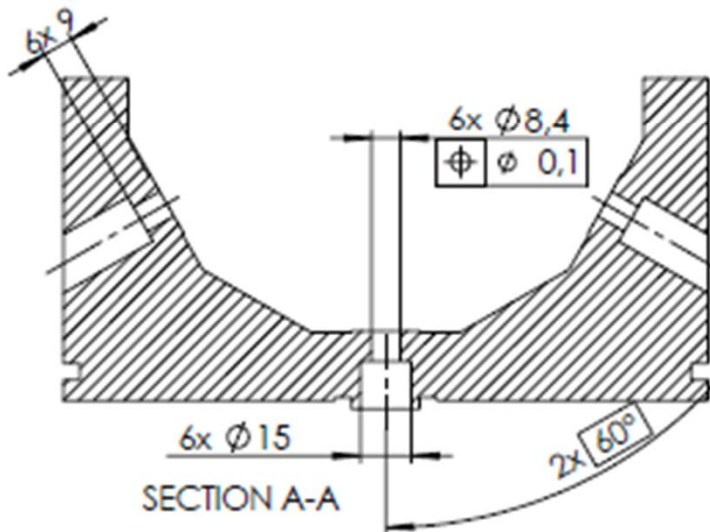
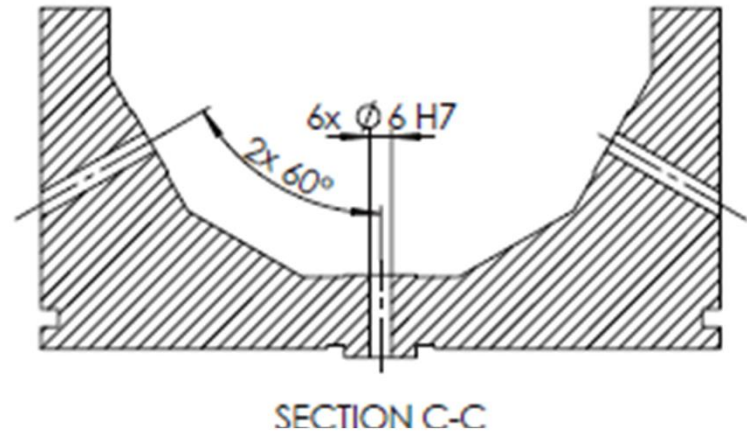
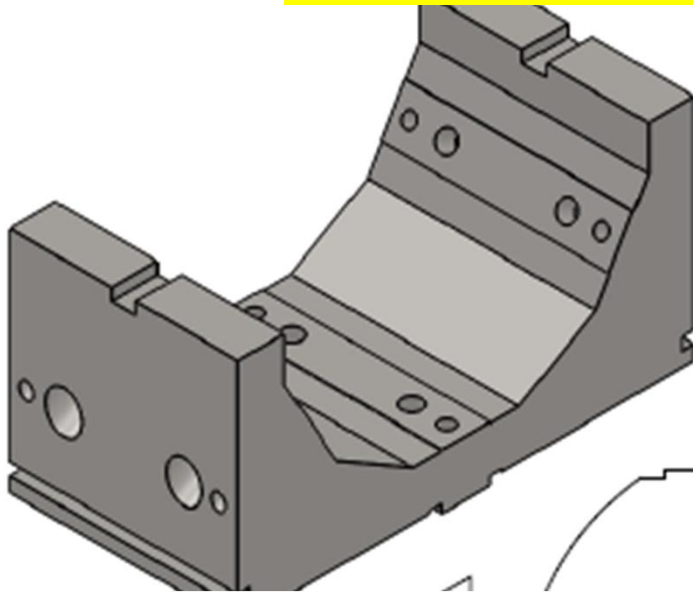
**Quadrupole**

# a MAX IV magnet block:

- Dismountable at horizontal midplane.
- all yoke parts = Armco low carbon steel.
- Quad and corr pole tips mounted over the coil ends.
- 6pole and 8pole magnet halves mounted into guiding slots in yoke block.
- Electrical and water connections located towards inside.



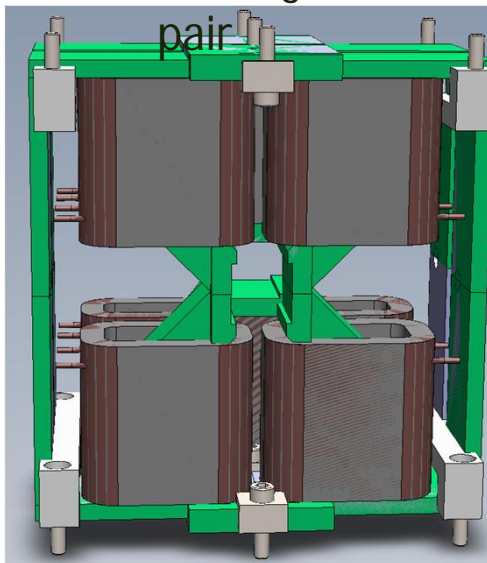
# Machining of the Sextupoles



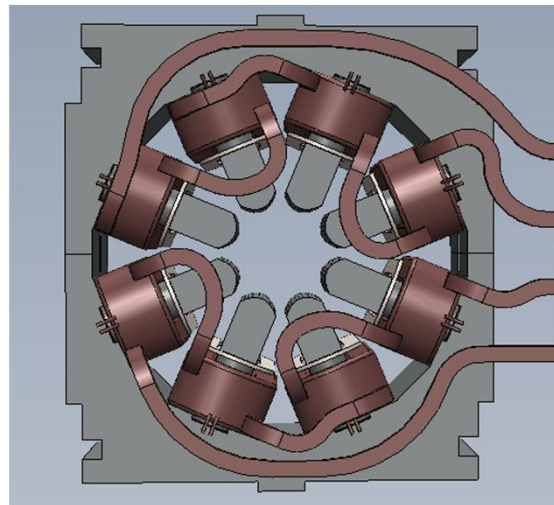
# Small magnets

- The smaller magnets (25 mm) define the chamber aperture
- All magnets are made in an upper and a lower half that may be opened in the mid plane

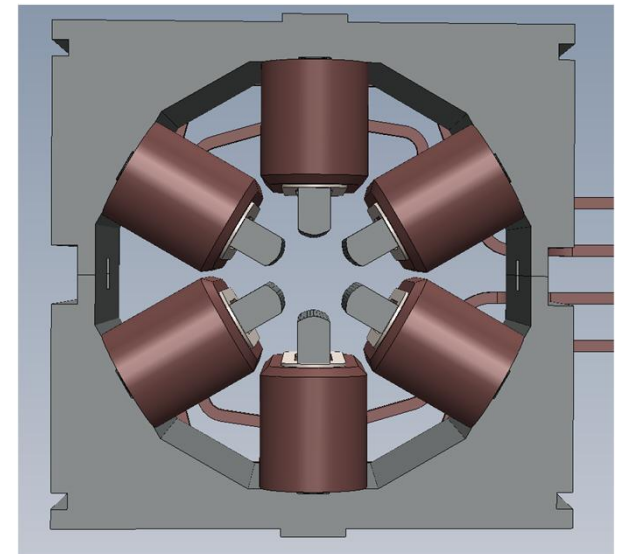
Corrector magnet



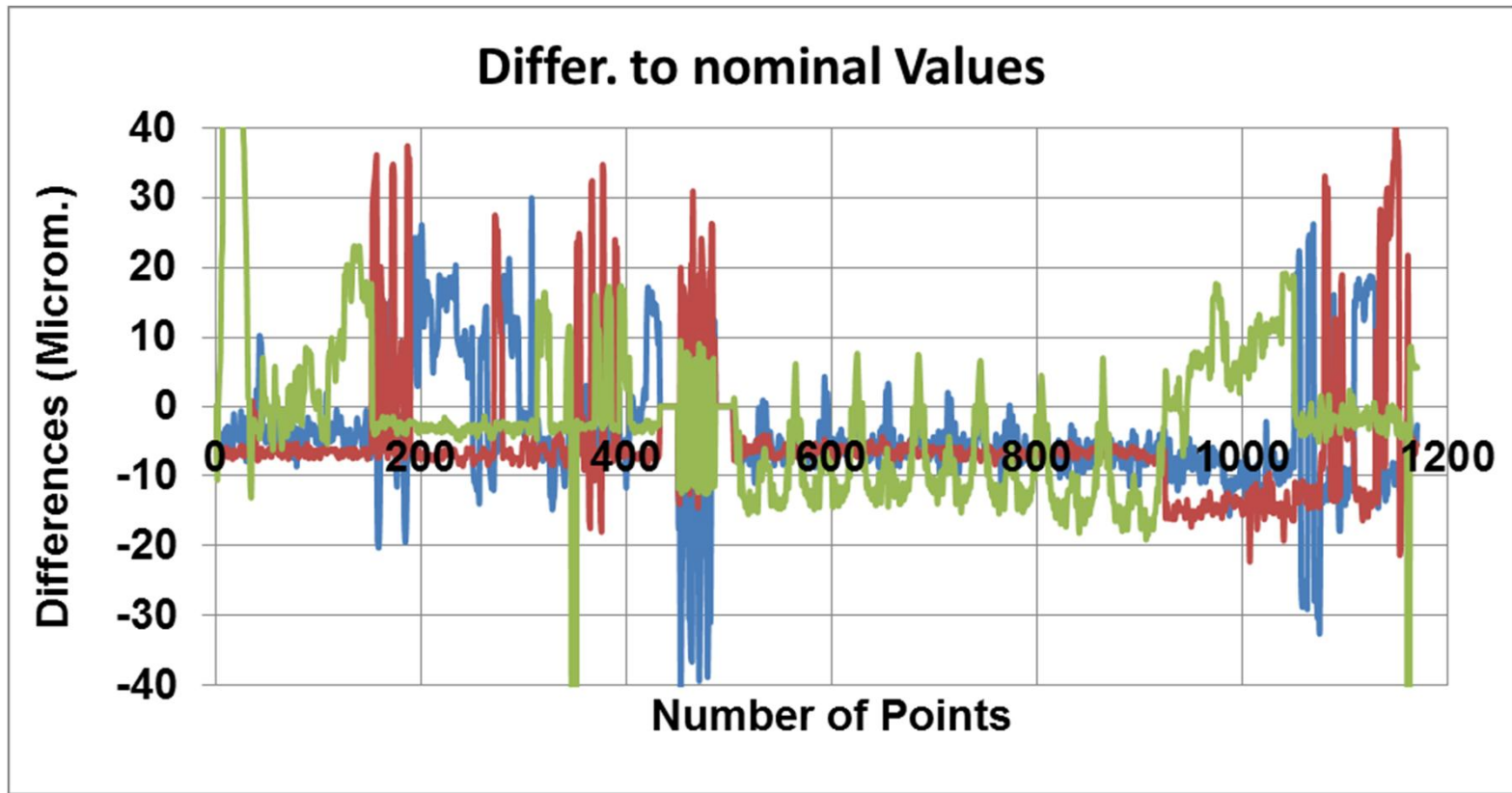
Octupole



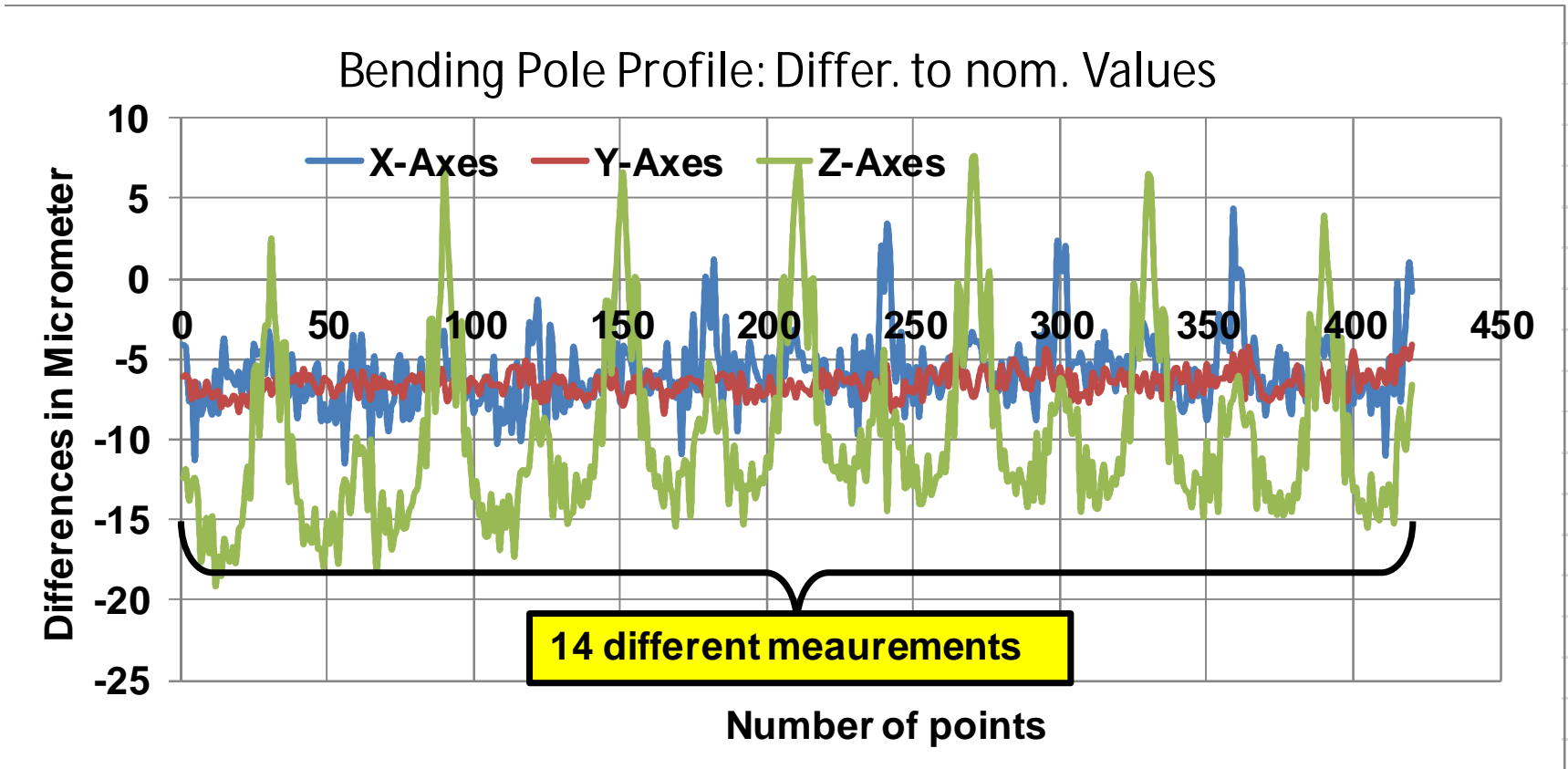
Sextupole



# Machining Accuracy

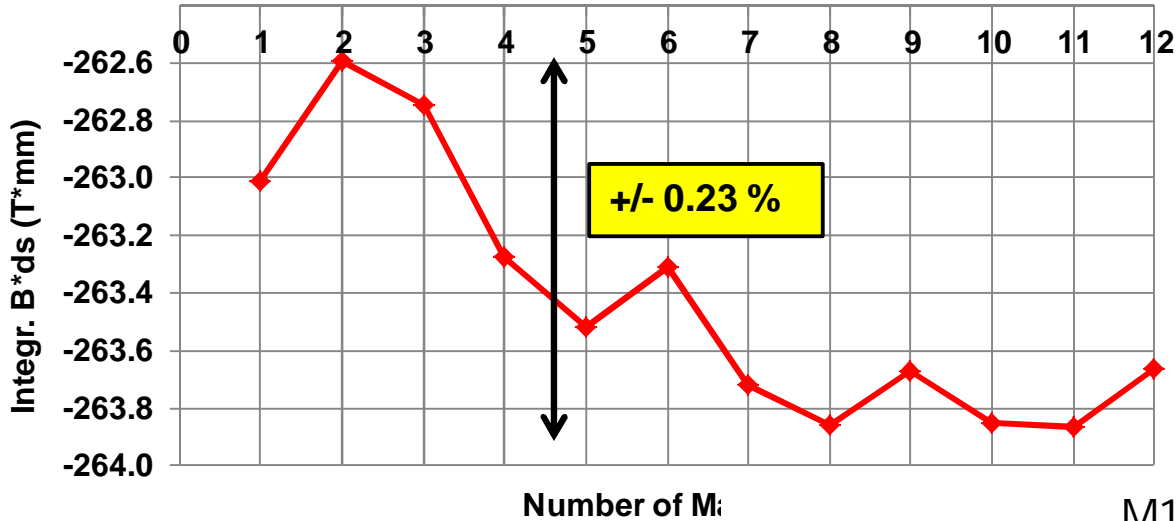


# Machining Accuracy

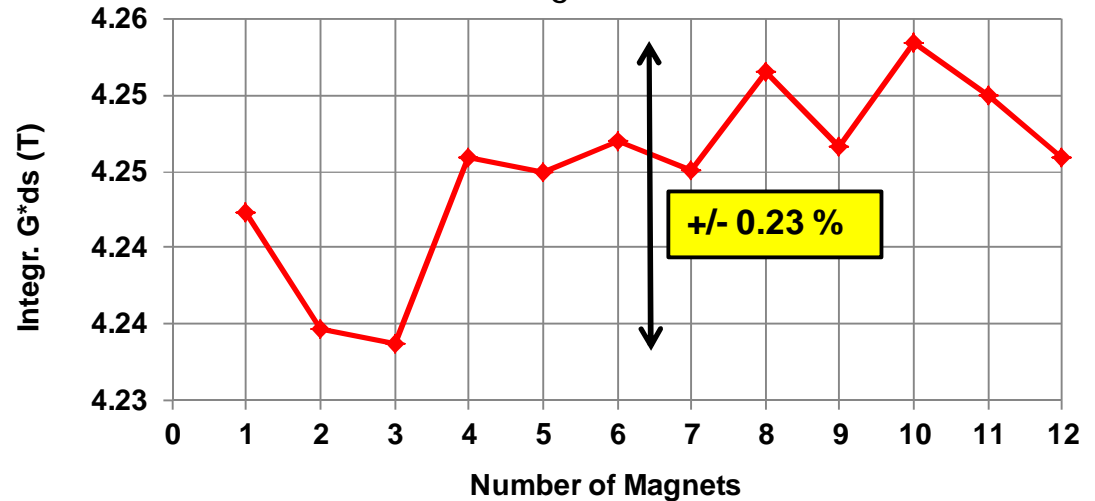


# Measurement Results (M1)

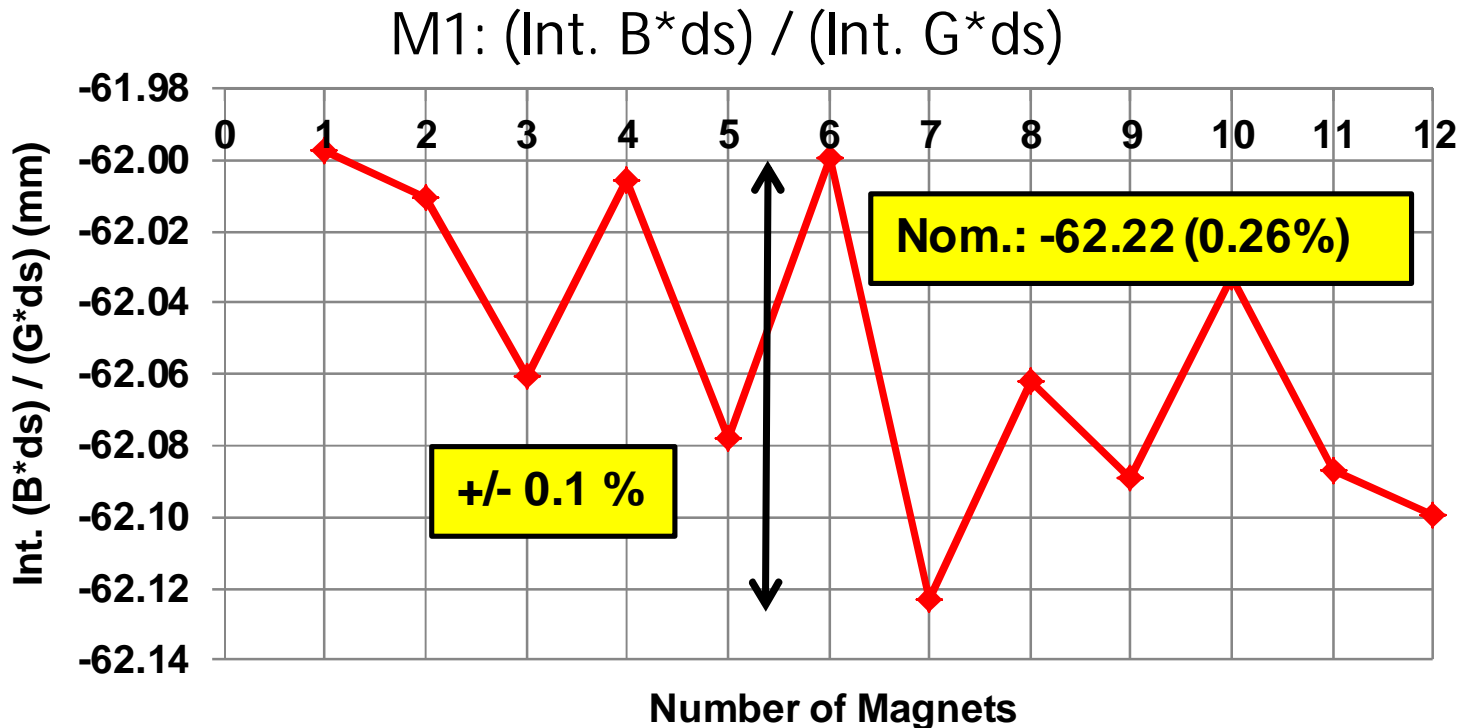
M1: Integr B\*ds



M1: Integr G\*ds



# Measurement Results (M1)

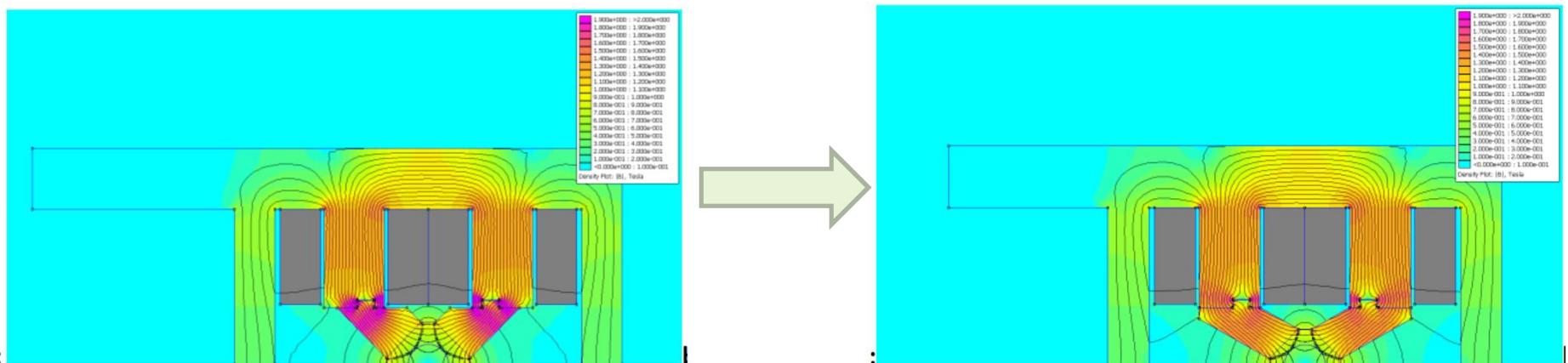


The difference can be adjusted with the pole face windings



# Rotating Coil Measurements

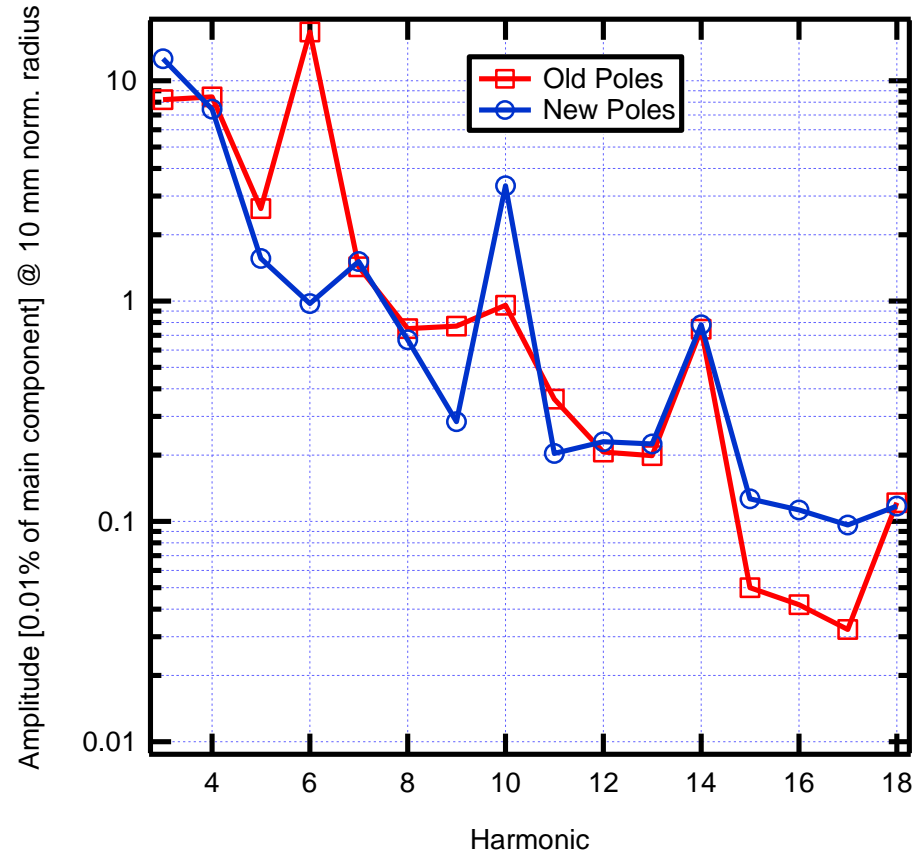
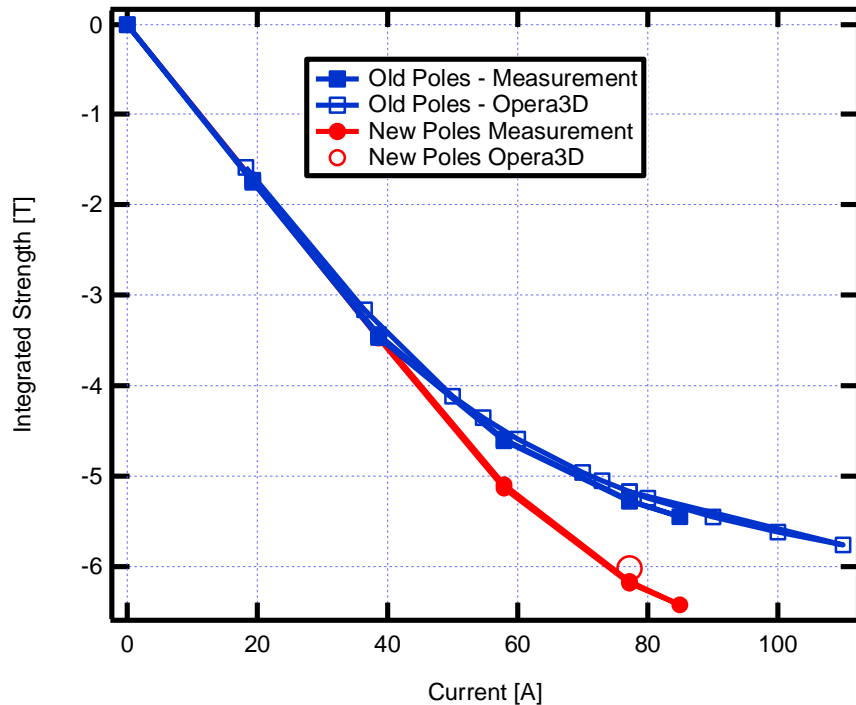
Early measurements indicated saturation problems in QF, QFms and led to a new design.



Images: Martin Johansson

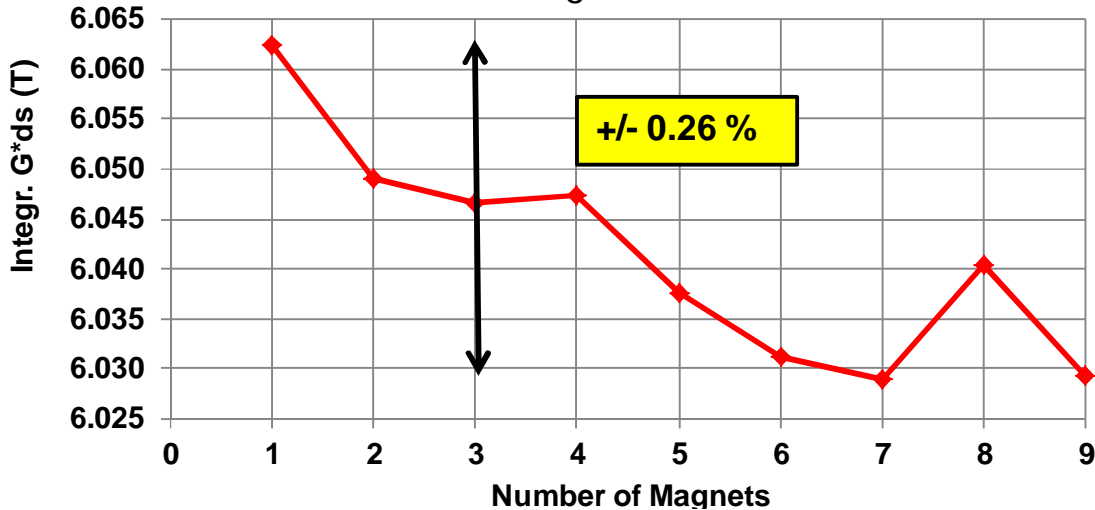
# Rotating coil measurements

New poles were manufactured, tested.  
New design is approved for production.

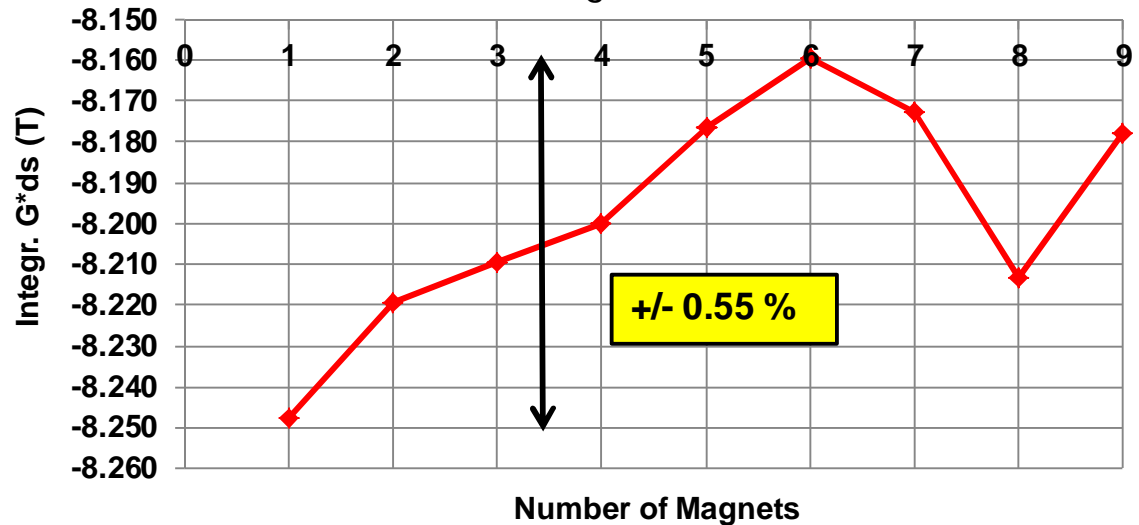


# Measurement Results (M1)

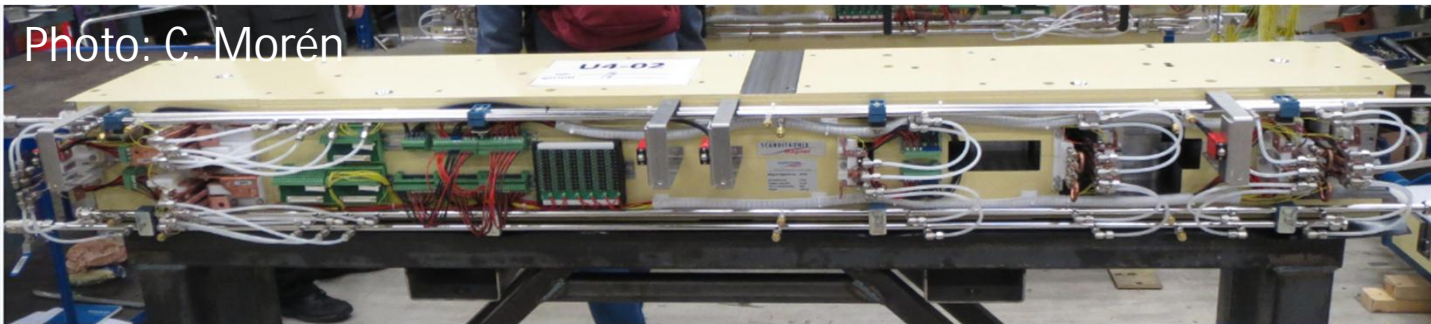
QDE: Integr. G\*ds



QFE: Integr. G\*ds



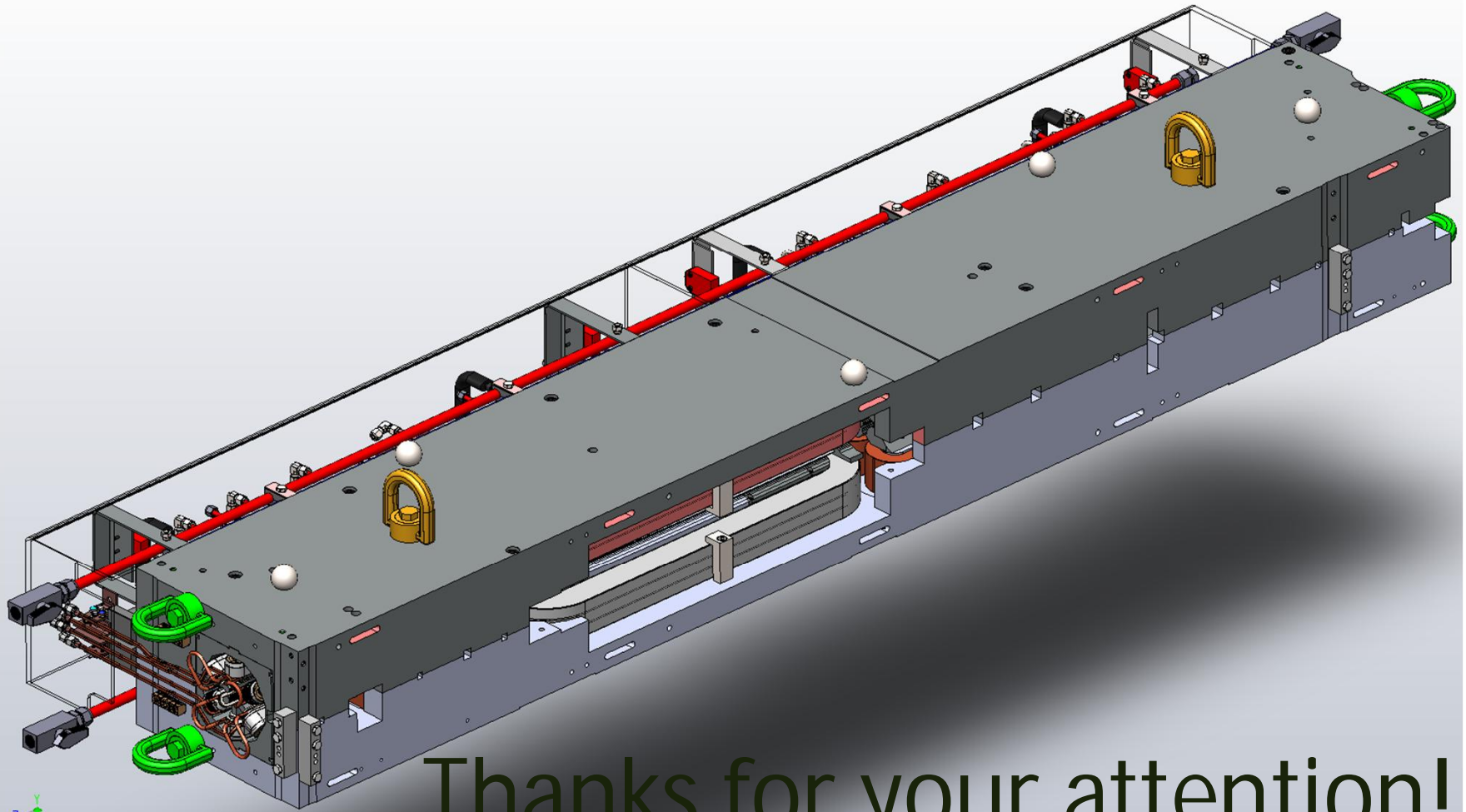
# 3 GeV Ring Magnets



- Series production ongoing
- All M1, M2 blocks machined
- About 50% of the U1, U2, U4, U5 machined
- Full Delivery until July 2014



# *MAX IV Magnets*



Thanks for your attention!