

#### E326: Non-Intercepting Diagnostics for High Intensity Beams and Computer Control

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#### **E326 Motivation**

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- FACET produced @(30 kA) beams
  - Punctured some foils, drilled through some diamond
- FACET-II expects to produce 100+ kA
- Future accelerators want to get to MA!

These accelerators pose diagnostic challenges:

- Materials in, or near the beam, are a non-starter
- Extremely short beams (FACET-II) need to be handled carefully to preserve quality



The future is both high quality and high intensity - diagnostics are needed

# **Edge Radiation Based Diagnostic**



- Great for measuring high-current beams: nonintercepting
- Ideal for computer control: single shot
- Edge Radiation generated at dipole magnet edges
- Interference between edges used to measure divergence and energy spread
  - Phase differences due to beam size minimal
- To be fast, diagnostic requires advanced image analysis



Continuous quantification of high-current beams, ideal for machine learning

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### **Convolutional Neural Network for real time diagnostic**

- Integral to generate image not tractable and numerical integration is "slow", O(mins)
- Convolutional Neural Networks excel at image analysis
- Examines entire image instead of lineouts
  no data is lost for speed
- Trained on simulation data that is generated offline - no sacrifice of fidelity or accuracy for speed
  - Understanding beam dynamics
    - Good SRW simulations
      - Good Image analysis
        - Good control

Quickly determine beam distribution from interference pattern using machine learning

 $I(\vec{x}) = \left| \int \vec{E}(\vec{x} - \vec{x}', p) \rho(\vec{x}', \sigma) \mathrm{d}\vec{x}' \right|^2$ 



Image from PARsE http://parse.ele.tue.nl/education/cluster2

## **Machine Learning Ecosystem at FACET-II**



Synergistic experiments, individual success enhances all research

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# **Experimental Layout**

- 14 ports spread across Dogleg, BC11, BC14 and BC20
  - Ports already exist in Dogleg and BC14
- Off the shelf camera objectives and filters, standard FACET gigE cameras, laser optomechanics
- "Divide and conquer" the accelerator

Gur

ector

Dogleg

Linac



# **Experimental Timeline - Prioritized tunnel hardware**

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	Oct 2020	Nov 2020	Dec 2020	Jan 2021	Feb 2021	Mar 2021	Apr 2021	May 2021	
Dogleg		2	3					4	
BC11	C	BC11	@ 90%	1	2	3			
BC14							2		
BC20				0	BC20 @	90%		1	

- 0) Design beam chambers
- 1) Install Beam chambers
  - Success: Beam chambers installed
- 2) Install optics
  - Success: Light/interference on cameras
- 3) Tune beam optics to check dynamic range
  - Success: cross check fringe contrast against traditional diagnostics
- 4) Start building and implementing ML model

Prioritizing tunnel hardware to meet FACET-II schedule

Readiness [%]	Beam Chambers	Optics	ML
Dogleg	100	90	5
BC11	50	70	5
BC14	100	60	5
BC20	0	50	5

Safety Review: Done Beam Requirements: Single bunch preferred

## Diagnostics and Observables, Future Evolution and Desired Upgrades

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Diagnostics and observables:

Current emittance diagnostics are sufficient

Future Evolution:

- Control! Both simple and novel
- Potential use in the dump at FACET-II
- Add to design of CSR chicane
- AWA has shown interest
- LCLS has shown interest too
- FACET-III could use this technique downstream of the plasma

Desired Upgrades:

- Laser heater to study coherence effects
  - Coherence effects change what you measure, not if you can measure
- Dipole pairs everywhere!



# Thanks! Questions?



1 slide: what is desired facility upgrades Backup slides:

- 1 slide: collaboration
- 1 slide: publications, students

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1 slide: experimental timeline: experimental design (90%) : date installation plan: date ready for Experimental safety review: date ready for installation: date Ready for commissioning: beam requirements

first science: beam requirements

2 phases of the program: prerequisites, date, etc.



1 slide: diagnostics and observables



1 slide: what are the science goals: indicate for each target time (ex. 6 mo, 1 year, 3 years), the definition of success for each goal